FURUNO

Installation Manual COLOR SECTOR SCANNING SONAR Model CH-37BB

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(TEHI) CH-37BB

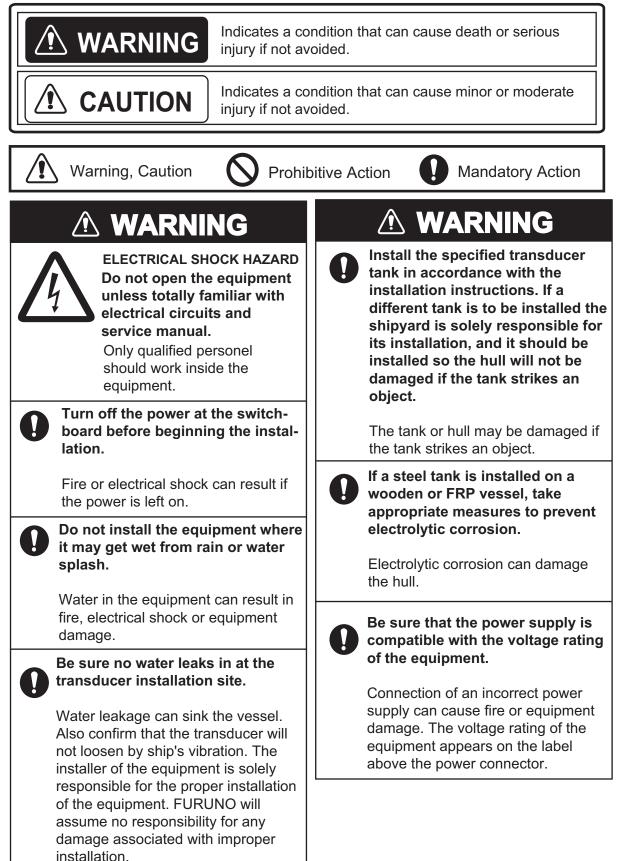
A : MAR. 2012 H : APR. 15, 2021



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▲ SAFETY INSTRUCTIONS

Read these safety instructions before you operate the equipment.



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Ground the equipment to prevent electrical shock and mutual interference.

Observe the following compass safe distances to prevent deviation of a magnetic compass:

	Standard compass	Steering compass
Transceiver unit	1.50 m	0.95 m

WORKING WITH THE SONAR OIL Precautions

- Keep oil away from eyes. Wear protective gloves when working with the oil. The oil can cause inflammation of the eyes.
- Do not touch the oil. Wear protective gloves when working with the oil. The oil can cause inflammation of the skin.
- Do not ingest the oil. Diarrhea or vomiting can result.
- Keep the oil out of reach of children.

Emergency

- If the oil enters eyes, flush with clean water about 15 min. Consult a physician.
- If the oil contacts skin, wash with soap and water.
- If the oil is ingested, see a physician immediately.

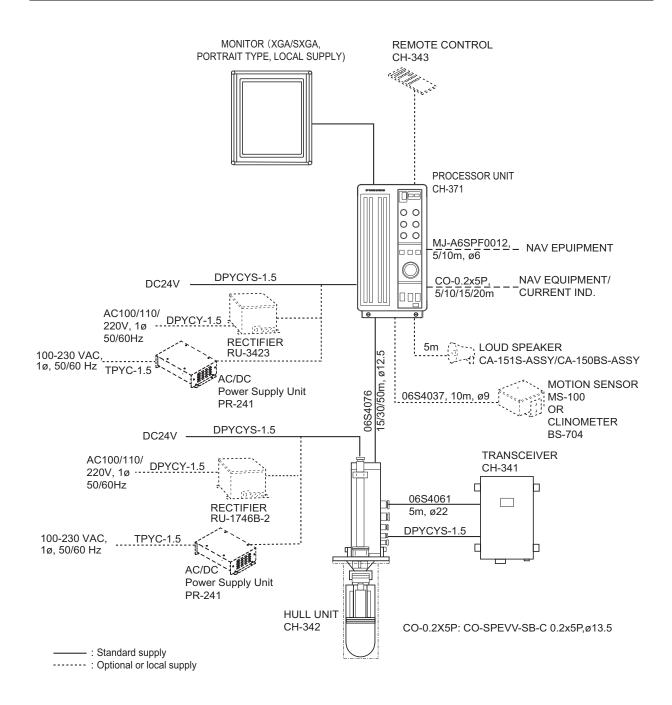
Disposal of oil and its container

Dispose of oil and its container in accordance with local regulations. For further details, contact place of purchase.

Storage

Seal container to keep out foreign material. Store in dark place.

SYSTEM CONFIGURATION



EQUIPMENT LISTS

Standard Supply

Name	Туре	Code No.	Qty	Remarks
Control unit	CH-371	-	1	
Transceiver unit	CH-341	-	1	60/113/162 kHz, select one
Hull Unit	CH-342	-	1	60/113/162 kHz, 24 VDC, Shaft length 1.17/2.2/3.8 m
Installation	CP06-01100	000-068-457	Select	Cable length: 15 m (standard supply)
materials	CP06-01110	000-068-458	one	Cable length: 30 m
	CP06-01120	000-068-459		Cable length: 50 m
	CP06-01102	006-563-250	1 set	For control unit
Spare parts	SP06-01501	001-166-030	1	

Optional Supply

Name	Туре	Code No.	Remarks
Remote control	CH-343	-	
Motion sensor	MS-100	-	
Clinometer	BS-704	-	
Rectifier	RU-1746B-2	000-030-439	100/110/220 VAC
Rectifier	RU-3423	000-030-443	100/110/220 VAC
AC/DC Power Supply Unit	PR-241	-	
Ferrite Core	OP86-11	001-594-450	For PR-241
Loudspeaker	CA-151S-ASSY	001-466-200	8Ω
	CA-150BS-ASSY	000-190-183	
Fairing	06-021-4502	001-159-790	For an FRP ship
Cable assembly	MJ-A6SPF0012-050C	000-154-053	64S4071-2, 5 m, 6 pin-6 pin
	MJ-A6SPF0012-100C	000-154-037	64S4071-2, 10 m, 6 pin-6 pin
	MJ-A6SPF0011-050C	000-159-690	03S9202-2, 5 m, 6 pin-4 pin
	MJ-A6SPF0011-100C	000-159-691	03S9202-2, 10 m, 6 pin-4 pin
5-pair twisted cable	CO-SPEVV-SB-C	000-560-451	5 m
	0.2 x 5P	000-560-452	10 m
		000-560-417	15 m
		000-103-868	20 m
48-core cable	06S4056	000-126-160	For extension of cable between hull unit and transceiver unit, specify length
Multi-core cable (12P+12P)	XES-SB 60/0.08×24P	001-255-400	
Replacement kit A	OP06-23-1	001-367-000	
Replacement kit B	OP06-23-2	001-367-020	

Name	Туре	Code No.	Remarks
Steel retraction tank	06-007-1570-2	600-715-702	1.0 m
	SHJ-0001-2	661-000-012	1.8 m
	06-007-1571-2	600-715-712	3.5 m
FRP retraction tank	06-021-4024	001-352-280	1 m
	06-007-1573-0	600-715-730	1.8 m
Aluminum retraction tank	OP10-5	000-019-283	1 m, with inst. materials
Raise/lower driving	CH-3422-60-2	006-547-010	60 kHz
unit	CH-3422-113/115-2	006-547-050	113 kHz
	CH-3422-162-2	006-547-070	162 kHz
Shaft	06-007-1591	001-261-030	3 m
Soundome	CH-3422-60-11	006-547-090	2.7 m cable (standard)
	CH-3422-113/115-11	006-547-150	
	CH-3422-162-11	006-547-180	
	CH-3422-60-22	006-547-100	3.7 m cable (option)
	CH-3422-113/115-22	006-547-160	
	CH-3422-162-22	006-547-190	
	CH-3422-60-38	006-547-110	5.3 m cable (option)
	CH-3422-113/115-38	006-547-170	1
	CH-3422-162-38	006-547-200	1

<u>Hull Unit</u>

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NOTICE

Do not apply paint, anti-corrosive sealant or contact spray to coating or plastic parts of the equipment.

Those items contain organic solvents that can damage coating and plastic parts, especially plastic connectors.

1.1 Hull Unit

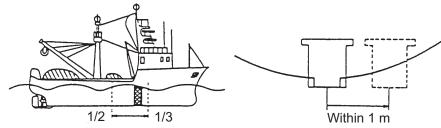
General mounting considerations

- Noise and air bubbles will affect performance.
- Keep the transducer away from oil. Oil can corrode the cable.
- Do not expose the transducer to hot water. Hot water can damage the transducer.
- Do not turn on the equipment with the transducer exposed to air. Exposing the transducer to air may damage it.

Installation position considerations

Discussion and agreement are required with the dockyard and ship owner in deciding the location for the hull unit. When deciding the location, take into account the following points:

 Select an area where propeller noise, cruising noise, bubbles and interference from turbulence are minimal. Generally, the point at 1/3 to 1/2 of the ship's length from the bow or near the keel is the best. On-the-keel installation is advantageous for minimizing oil consumption in comparison with off-the-keel. If the hull unit cannot be installed on the keel, the center of the retraction tank should be within 1 meter of the keel to prevent a rolling effect.



- Select a place where interference from the transducers of other sounding equipment is minimal. The hull unit should be at least 2.5 meters away from the transducers of other sounding equipment.
- An obstacle in the fore direction not only causes a shadow zone but also aerated water, resulting in poor sonar performance. Be sure to locate the transducer well away from any obstacle in the fore direction.

Mounting method

A typical mounting method is shown in the outline drawing at the back of this manual. Consult ship's owner, dockyard and user to determine appropriate mounting method. Pay attention to safety (strength, watertightness) first, followed by ease of maintenance and inspection.

Tank length

Shorten the transducer tank so the transducer is lowered into water as deep as possible.

Pay particular attention to the tank length (Lt). Determine the length of the main shaft as described in the paragraph.

Note 1: Do not shorten the 1 meter retraction tank. Shortening it may also necessitate shortening of the top part of the main shaft, thereby destroying the watertight construction of the 1.17 meter shaft.

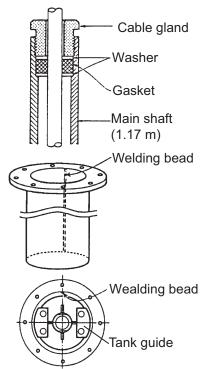
Note 2: When the retraction tank is constructed locally, finish it so that welding beads do not protrude on the inner surface of the tank. The tank guide will hit the bead, burning out the raise/lower motor. Also, do not position the welding bead in the ship's fore-aft line.

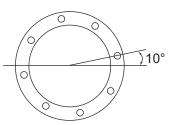
Note 3: Use of other manufacturer's tank is permitted. However, the dimensions should be the same as those in the transducer tank outline drawing.

Mounting of transducer tank

Install the transducer tank referring to the hull unit outline drawings at the back of thismanual.

Note: Locate one of the bolt holes 10° to port to minimize mechanical shock at the raise/lower block during pitching and rolling.





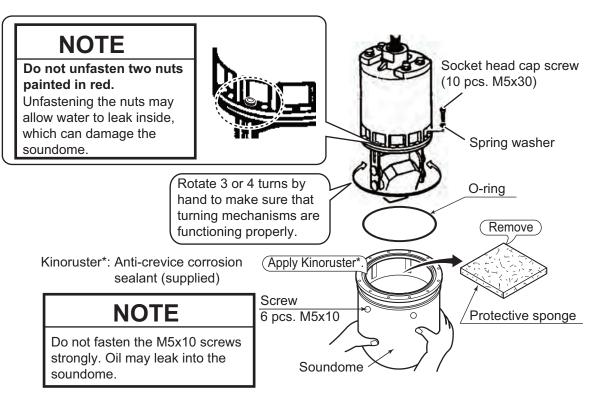
Assembling and mounting of hull unit

The hull unit is shipped disassembled as the parts. Assemble the hull unit as shown in the procedure below.

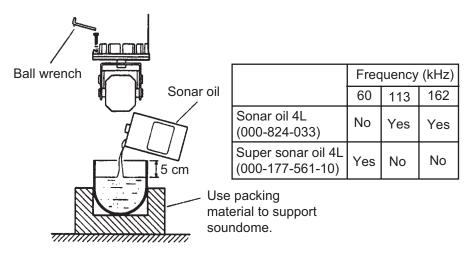
Necessary tools

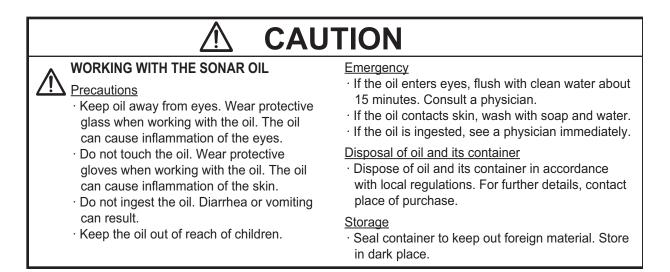
Name	Specification	Remarks
Wrench	For M10 (Hex. size 17 mm)	
Wrench	For M20 (Hex. size 20 mm)	
Pipe Wrench	55 mm	
Ball Wrench	Hex size 4 mm	Supplied with hull unit kit

1. Unscrew ten pieces of socket head cap screws with the ball wrench (supplied) to detach the soundome.

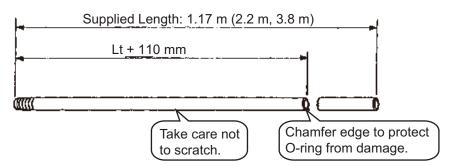


2. Fill the soundome with sonar oil 6 cm below the top of the dome. (Use only the specified sonar oil. Use of other sonar oils may affect performance.) Reattach the soundome.



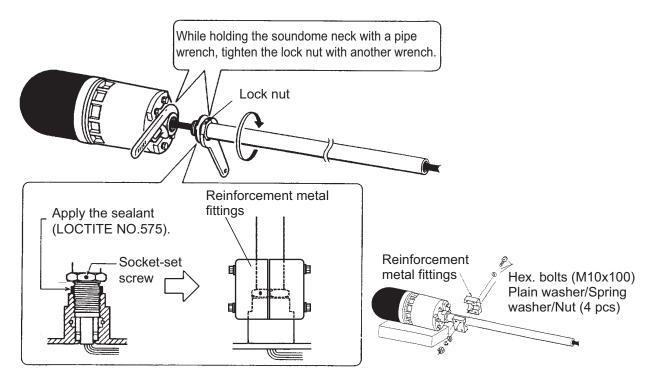


3. Shorten the main shaft by the length of Lt + 110 mm, where Lt is the length of the retraction tank. When the retraction tank length is 1 meter do not shorten the 1.17 meter main shaft.

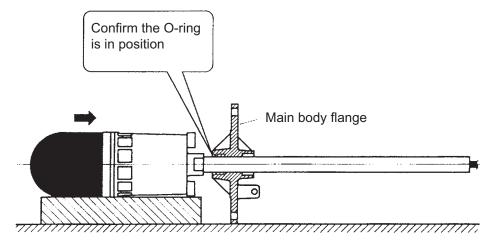


- 4. Fasten the main shaft to the soundome assembly as follows;
 - a) Screw the lock nut onto the main shaft.
 - b) Pass the transducer cable through the main shaft.
 - c) After fully screwing the main shaft into the soundome neck, unscrew it by four turns and apply the supplied sealant (LOCTITE NO.575) to the threads.
 - d) Screw in the main shaft completely, then tighten the lock nut with a wrench.
 - e) Remove any excess sealant with a waste cloth. The sealant does not harden when exposed to air.
 - f) Tighten the socket-set screw on the lock nut.

g) Fasten two reinforce metal fittings to connect the main shaft and the soundome assembly securely (not using the stopper washer).

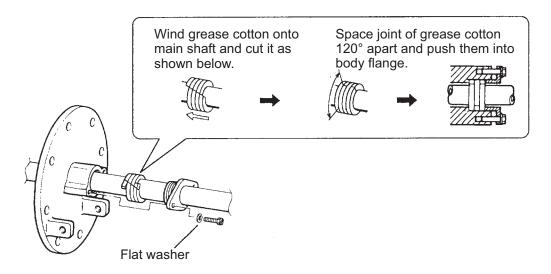


5. Clean the main shaft and pass it through the main body flange.

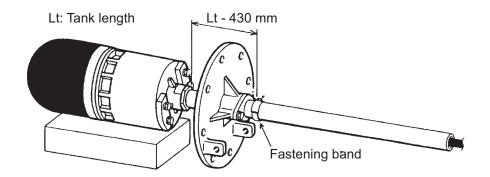


1. MOUNTING

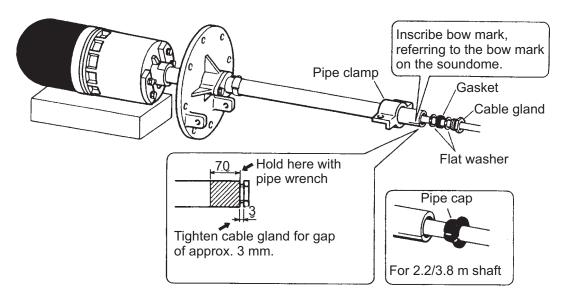
6. Set the grease cotton to the main body flange and tighten the grease cotton retainer temporarily.



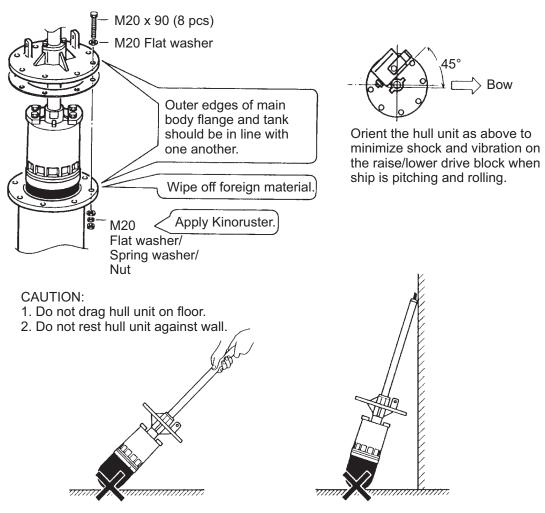
7. Temporarily fasten the fastening band onto the main shaft at the location shown below.



8. Inscribe bow mark at the top of the main shaft. Pass pipe clamp through the main shaft and install washer, gasket and cable gland.



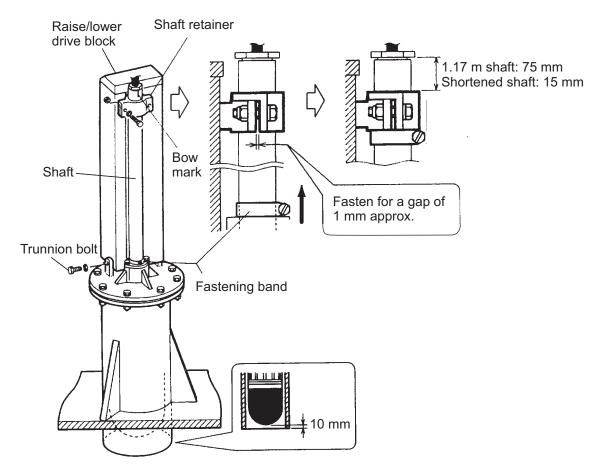
9. Fasten the hull unit to the transducer tank, orienting it so the ship's fore-aft line crosses the front panel of the raise/lower drive block at an angle of approximately 45 degrees.



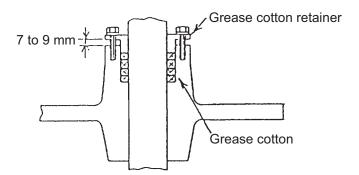
10. Install the raise/lower drive block as follows;

- a) Rotate the main shaft so the bow mark faces ship's bow.
- b) Install the raise/lower drive block onto the main body flange.
- c) Fix the main shaft with the shaft retainer.
- d) Loosen the fastening band, slide it up to the shaft retainer and fasten it.
- e) Check that the distance from the top of the main shaft to the top of the shaft retainer is as follows:
 - 1.17 m main shaft: 75 mm
 - Main shaft cut at Lt + 110 mm: 15 mm

If not as shown above, loosen shaft retainer and fastening band to adjust the distance. This will place the bottom of the soundome 10 mm above the bottom of the retraction tank when the soundome is retracted.



11. Tighten the grease cotton retainer for a gap of 7 to 9 mm.

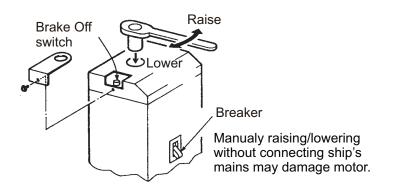


Checking manual raise/lower of transducer with hand crank

Perform this check after all wiring has been completed. Ship's mains power must applied to the hull unit, otherwise the magnetic brake of the raise/lower motor activates, disabling the manual raise/lower gears.

- 1. turn off the breaker on the hull unit.
- 2. Detach the brake-off switch cover.
- 3. Set hand crank to the shaft gear and turn it while pressing the brake-off switch.

4. The transducer should raise/lower smoothly with even force in upper to lower limits. If not, the centers of the main body flange and the retraction tank are not aligned. Adjust the hull mounting position if necessary.



1.2 Transceiver Unit

Mounting considerations

- The mounting location should be well ventilated and dry.
- The unit can be mounted on a bulkhead or the deck. The unit weights 8.5 kg so reinforce the mounting location if necessary.

To install the unit, refer to outline drawing D-2. Secure the maintenance space shown in the outline drawing for ease of maintenance and service.

1.3 Processor unit

Mounting considerations

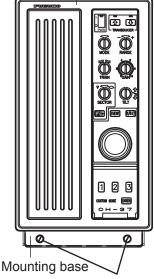
Select the mounting location considering the following conditions:

- Select a location where the processor unit can easily be operated while observing the fishing ground or area surrounding the vessel.
- Locate the unit at least 1 meter away from equipment which contains magnets (radar magnetron, loud-speaker).

Mounting Procedure

- 1. Loosen two bolts at front of processor unit and remove the chassis from mounting base.
- Fix the mounting base with six tapping screws \$\overline{6}\$ x 20.
- 3. Put the chassis onto the mounting base.
- 4. Push the chassis toward the mounting base end.

Processor unit



Loosen these bolts and separate mounting base.

5. Fasten the chassis to mount base with two bolts removed at step 1.

1.4 Monitor

The portrait type monitor MU-151C or a commercial monitor can be used. The MU-151C is designed to be flush mount in a console.

When a commercial monitor is used, it should meet the following specifications;

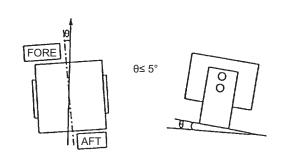
- Input signal: Analog RGB separated
- Resolution: XGA (1024 x 768) or SXGA (1280 x 1024), 60 Hz
- Signal level: 0.7 Vp-p, analog positive, Synchronization: TTL level
- Impedance: Video signal: 75 ohm, Horizontal 47 ohm, Vertical 47 ohm

1.5 Motion Sensor

The Motion Sensor MS-100 (option) measures ship's pitching and rolling angles. It is free from error caused by ship's vertical and horizontal motion. Therefore, it can be installed at any convenient location. However, ship's semi-permanent inclination due to loading imbalance cannot be detected. Compensate for this as described in Chapter 3.

Mounting considerations

- Vibration in the mounting area should be minimal.
- Locate the unit away from areas subject to water splash.
- The ambient temperature should not exceed 50°C (122°F).



Mounting procedure

Orient the FORE mark on the unit toward the ship's bow and mount the unit level to within 5 degree in all directions.

1.6 Clinometer

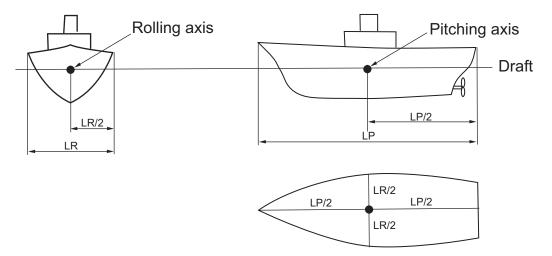
The clinometer BS-704 (option) detects ship's inclination caused by ship's rolling and pitching. Its output is used to stabilize the sonar beam against rolling and pitching.

The clinometer measures the inclination of the ship by sensing the direction of gravity acted on it, therefore when installed on a ship, it should be placed on or near the rotation axes of the ship's rolling and pitching. If it is placed away, upward from the axes, the measured value becomes larger than the correct value. On the contrary, if it is placed below the axes, the measured value becomes smaller. The same can be said when it is placed far to the left or right from the axes.

The rotation axes of pitching and rolling are theoretically considered to be located on the level of the ship's draft and in the center of ship. In other words, it can be said as follows;

- 1) Vertical position of the pitching and rolling axes is on the draft level of the ship.
- 2) Horizontal position of the rolling axes is in the center of ship's port-stbd line.
- 3) Horizontal position of the pitching axes is in the center of ship's fore-aft line.

From 1), 2) and 3) above, the crossing point of the two axes is indicated by the black dots in below. The clinometer should be mounted as close as possible to this point.



Note 1: The vicinity of the hull unit (on the ship's bottom) is too low and should be avoided, since the polarity of the measured value is reversed.

Note 2: When it is impossible to install the clinometer on the intersecting point of both rolling and pitching rotational axes, a special effort should be made to install it at place where the vertical distance to the intersecting point is minimum.

Note 3: The clinometer should be installed on the horizontal plane.

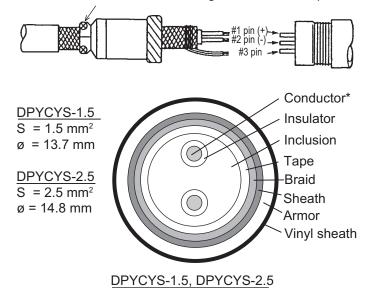
Note 4: Install the clinometer with the bow mark pointing in toward the ship's bow.

1. MOUNTING

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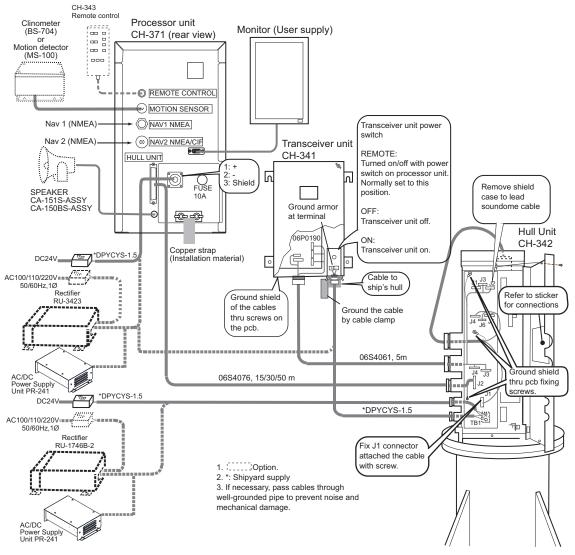
2.1 Wiring Among Units

- The figure on the next page shows wiring among units.
- The signal cables are fitted with connectors. Connect the cables to the display, transceiver and hull units referring to the interconnection diagram and the drawing on page S-1.
- The power cable should be arranged locally. Use power cable type DPYCYS-2.5 and DPYCYS-1.5 (both Japan Industrial Standard cables) or equivalent cables. Attach supplied power connector as shown below.



Ground armor through connector clamp.

- Install the main switch for the sonar where it can be easily accessed. Turn off this switch when the sonar is not being used, to reduce power consumptions and to keep the transducer from slipping by vibration.
- For AC mains, use rectifiers RU-3423 or AC/DC power supply unit PR-241 for the processor unit and transceiver units, and RU-1746B-2 or AC/DC power supply unit PR-241 for the hull unit.



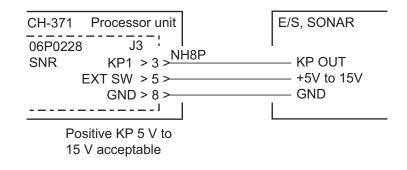
Use below rectifiers or AC/DC power supply unit for AC mains. RU-3423: for processor unit RU-1746B-2: for transceiver and hull unit

PR-241: For processor, transceiver and hull unit

2.2 Synchronizing Transmission with Echo Sounder or Other Sonar

To synchronize transmission of the CH-37BB with an echo sounder or other type of sonar, connect it as shown below.

Connections for synchronizing Tx with other E/S, sonar

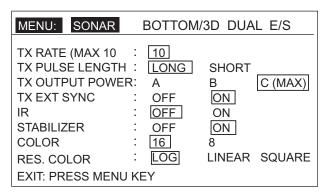




Processor unit (right side view)

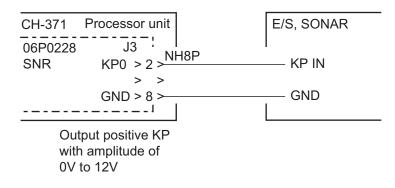
Menu setting

- 1. Press the MENU key.
- 2. Select SONAR at the top of the menu.



- 3. Set TX EXT SYNC to ON.
- 4. Press the MENU key.

Note: Outputting KP of CH-37BB to other sonar or echo sounder



2. WIRING

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3. ADJUSTMENTS

3.1 General Checks

Check Item	Check Point, Rating
Retraction tank level	On-keel Installation Off-keel Installation Water level Note: Do not cut the keel.
Clearance between transducer and bottom of retraction tank when transducer is com- pletely retracted by hand crank.	10mm
Transducer travel (lowered by hand crank) Note: For maintenance, a clearance of approximately 1 meter is required under the bottom of the transducer.	400 travel: Minimum 30cm
Manual raise/lower of transducer	Transducer can be raised/lowered smoothly with hand crank.
Transducer heading	Bow mark on the shaft sleeve should face ship's bow. BOW
Wiring check	 All cables are correctly connected. All lead wires are tightly fixed with contact pins or crimp-on lugs. All screws are firmly fastened. Cables are firmly secured. Cable shields are properly grounded.
Rejecting source of noise and interference	 Noise generating machinery (motor, radiotele- phone, TV set, etc.) are not placed nearby. Magnetic devices are not placed in the vicinity of processor unit.
Ground	Each unit is grounded with a copper strap.
Ship's mains voltage	Ship's mains voltage is stable 24 VDC.
Watertightness	Water should not leak from the main body flange or along the main shaft.
Heading alignment	A target is displayed on the correct bearing.

3.2 Adjustment of Transceiver Unit

Selecting audio frequency

Select audio frequency of 1000 Hz or 900 Hz by jumper connector JP2 on pcb 06P0192 in the transceiver unit. The default setting is 1000 Hz. Refer to Figure 3-1 for the location of JP2.

Signal offset adjustment

When noise appears on the screen, adjust R61 (offset) on pcb 06P0192. Turning R61 clockwise removes low level signals in a similar way to the CLUTTER control on the processor unit. (While the CLUTTER control on the processor unit eliminates low level signals without changing signal level of strong signals, R61 shifts signal level of all signals.) When the offset adjustment is necessary, set R61 fully counterclockwise. Refer to Figure 3-1 for the location of R61.

Horizontal beamwidth

When the user wishes echoes to be displayed in high resolution, turn R40 on pcb 06P0192 clockwise to sharpen horizontal beamwidth. Do not turn it excessively clockwise, or an echo which should be displayed as a single solid mass may become hollow or split into smaller, fewer masses. Normally, set R40 at the midpoint of its travel.

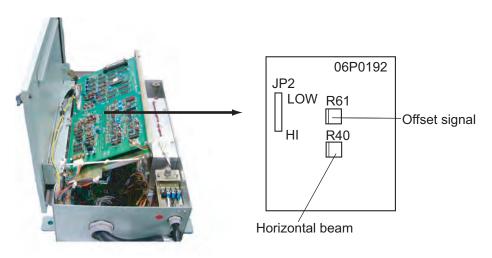
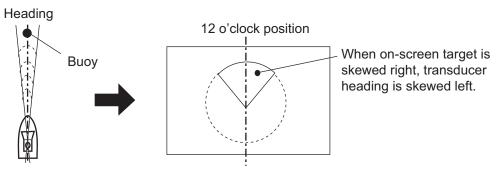


Figure 3-1 Transceiver unit, cover opened

3.3 Heading Alignment

1. Locate a target (buoy, etc.) in the bow direction and display it on the screen at close range. The heading alignment is correct when the target is displayed at 12 o'clock on the screen.

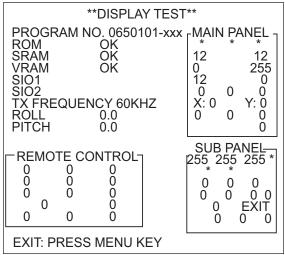


- 2. When the heading alignment is incorrect, loosen four bolts on the shaft retainer and then rotate the main shaft to align heading.
- 3. Tighten bolts.

3.4 Adjustment of Motion Sensor and Clinometer

When the ship has a semi-permanent inclination, offset it as follows. Inclination of up to 10° can be corrected.

- 1. Turn on the power while pressing the **MENU** key. Release the **MENU** key when you hear a beep.
- 2. Select [DISPLAY TEST] then press the **MENU** key.



- 3. Read [ROLL/PITCH] angles from the display.
- 4. By using a clinometer or other means, measure ship's semi-permanent inclination angle. Take the polarity of the angle as follows;

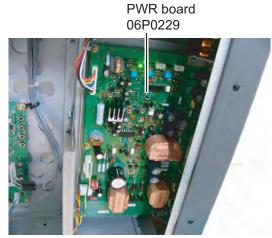
<u>Stern view</u>				
			+	-
	P	ROLL	STBD UP	STBD DOWN
	\$\$ ID \$\$	PITCH	Sterm UP	Sterm DOWN
- 0 -	. 0 -			

5. Adjust the potentiometers R35 (ROLL) and R36 (PITCH) on the MAIN board (06P0227) in the processor unit so the angle readout on the screen agrees with the angles measured at step 4.

3.5 LEDs Status

Processor unit

Range	Output power	Tilt	Tx Rate
400 m	C (max.)	0°	10



Processor unit, right side view

MAIN board 06P0227 SNR board 06P0228

Processor unit, left side view

РСВ		LED		Remarks
FOD	No.	Signal	Status	Remarks
MAIN	CR2	+5V	Lit	
06P0227	CR4	+12V	Lit	
	CR5	-12V	Lit	
SNR	CR4	L CONT	Off	Off except when transducer is being lowered.
06P0228	CR7	TR CLK	Flickers	Flickers while transducer TILT lever is pressed; off while TILT lever is released.
	CR9	TI CLK	Flickers	Lights momentarily when the transducer is trained to 0° direction.
	CR12	TR 0°	Flickers	Lights momentarily when the transducer is trained to 180° direction.
	CR14	TR 180°	Flickers	Lights momentarily when the transducer tilt angle is +180°.
	CR16	TI +10°	Off	Lights momentarily when the transducer tilt angle is $+10^{\circ}$ or 90° .
	CR17	TI 190°	Off	Lights momentarily when the transducer tilt angle is +90° or 190°.
	CR20	HULL	Lit	Lights while ship's mains is supplied to the hull unit.
	CR21	KP	Flickers	Flickers during KP transmission.

РСВ	LED			Remarks			
FOD	No. Signal		Status	iveniai va			
PWR	CR21	+5V	Lit				
06P0229	CR22	+12V	Lit				
	CR25	IN HL	Off	Lights when the over voltage protector operates.			
	CR26	+115V	Lit	Power supply for color monitor			
	CR27	-12V	Off	Lights momentarily when the over voltage protector for the -12V line operates.			
	CR30	5V	Off	Lights momentarily when the over voltage protector for the 5V line operates.			

Transceiver unit

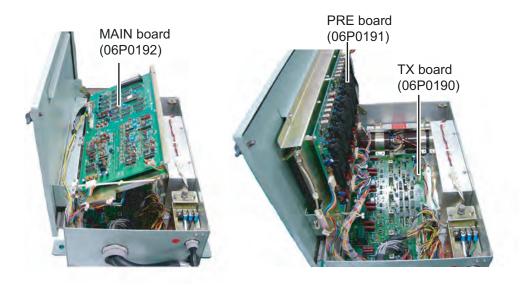


Table 3-3 LEDs in the transceiver unit

РСВ	LED			Remarks		
FCB	No.	Signal	Status	Remarks		
TX board	CR11	+5V	Lit			
06P0190	CR12	+12V	Lit			
	CR13	+130V	Lit			
	CR39	TX1	Flickers	Flickers during transmission		
	CR40	TX12	Flickers			
	CR41	TX11	Flickers			
	CR42	TX2	Flickers			
	CR43	TX3	Flickers			
	CR44	TX10	Flickers			
	CR45	TX9	Flickers			
	CR46	TX4	Flickers			
	CR47	TX5	Flickers			
	CR48	TX8	Flickers			
	CR49	TX7	Flickers			
	CR50	TX6	Flickers			
PRE board	CR1	+5V	Lit			
06P0191	CR2	+12V	Lit			
	CR3	-12V	Lit			

3. ADJUSTMENTS

РСВ	LED			Remarks
FCB	No.	Signal	Status	Remarks
MAIN	CR1	+5V	Lit	
board	CR2	+12V	Lit	
06P0192	CR3	-12V	Lit	
	CR4	AUD	Flickers	Flickers against audio signal
	CR16	FS	Lit	FS signal
	CR17	TVG	Flickers	Digital TVG signal
	CR18	LCLK	Lit	TVG signal latch clock
PWR	CR9	-12V	Lit	
board	CR10	+12V	Lit	
06P0172	CR11	+5V	Lit	
	CR12	+130V	Lit	

Hull unit



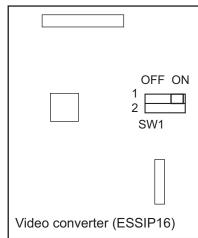
DRIVE board (06P0193)

РСВ	LED			Remarks				
FCB	No.	Signal	Status					
DRIVE board	CR12	TR 0°	Flickers	Light momentarily when transducer is trained in 0° direc- tion.				
06P0193	CR13	TR 180°	Flickers	Lights momentarily when the transducer is trained in 180° direction.				
	CR14	TI +10°	Off	Lights momentarily when the transducer is tilted to +10°C or 90°.				
	CR15	TI 90°	Off	Lights momentarily when the transducer is tilted to 90°.				
	CR16	+13V	Lit					
	CR18 TR CLK Lit		Lit	Lights when the transducer is being trained.				
	CR19	TI CLK	Off	Lights while the TILT lever is pressed, goes off when the TILT lever is released.				
	CR20	+13V	Lit					

3.6 Monitor Size Setting

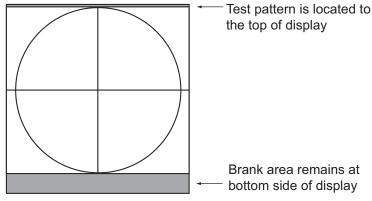
The CH-37BB is set at the factory for connection to a monitor of XGA resolution. For SXGA resolution, change the monitor resolution setting as shown below.

- 1. Confirm thet the main switch of processor unit is turned off.
- 2. Unfasten the screws at the left side of the processor unit to remove the left side cover.
- 3. Set the DIP switch SW1-#1 on the Video Converter board (ESSIP-16) according to the monitor connected, refering to the figure below.

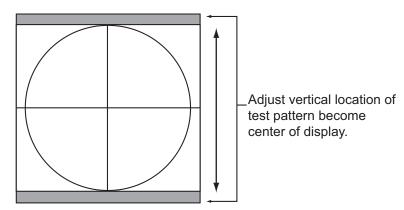


SW No.	XGA	SXGA
#1	OFF	ON
#2	OFF	OFF

- 4. Fasten the cover.
- 5. Press the **POWER** key while pressing the **MENU** key



6. Press \downarrow to select [TEST PATTERN], then press the **MENU** key.

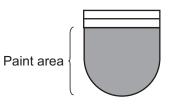


7. Turn the power off pressing the **POWER** key.

3.7 Soundome Painting

When the soundome is painted to keep marine life off the transducer, observe the following precautions:

Use only anti-fouling paint type SEATENDAR 20 (Manufacturer: Chugoku Marine Paint Co., Ltd., Japan).



Paint only the plastic portion of the dome. Painting the metal parts causes corrosion.

4. SYSTEM MENU

System menu should be customized for user's convenience.

- 1. Turn on the power while pressing the [MENU] key.
- 2. Select SYSTEM SETTING and press [MENU] key.

** SYS	** SYSTEM SETTING **							
3D DISPLAY	:	OFF	ON					
SHIP'S POSITION	:	OFF	L/L	LOP				
CURRENT DATA	:	OFF	FLOW FROM	FLOW TO				
DEPTH DATA	:	OFF	ON					
HEADING INDICATION	:	OFF	TRUE	AZ				
NORTH MARK	:	OFF	ON					
TRACK	:	10R	20R					
HDG/SPD DATA	:	NAV	CI					
NAV DATA	:	GPS	LORAN C	LORAN A				
		DR	DECCA	OTHERS				
DATA FORMAT FOR NAV2	:	NMEA	CIF					
CIF BAUD RATE	:	1200	2400	4800				
TVG CORRECTION	:	OFF	1/2	1				
UNIT	:	m	ft fa	HIRO				
V-MODE MANUAL TRAIN	:	HALF	FULL					
DEGAUSSING INTERVAL	:	30 SEC						
FACTORY SETTING	:	NO	YES					
EXIT : PRESS MENU KEY								

- 3. Select items and options with the arrow keys.
- 4. To return to normal operation, restart the unit.

Table 4-1	System	setting	menu	description

Item	Description
3D display	Turns 3D mode on/off
SHIP'S POSITION	Turns position indication on/off and selects position format, lati- tude and longitude or Loran LOP
CURRENT DATA	Turns current (tide) data on/off
DEPTH DATA	Turns depth indication on/off
HEADING DISPLAY	Turns heading indication on/off and selects its format; true bearing or azimuth (16 azimuth bearing)
NORTH MARK	Turns north marker on/off
TRACK	Select length of course line plotting; 10R (ten times the range in use) or 20R (twenty times the range in use)
HDG/SPD DATA	Select source of data to be used to plot course line; NAV (Navigator), CI (Current Indicator)
NAV DATA	Selects source of data; GPS, Loran C, Loran A, DR, Decca, others
DATA FORMAT FOR NAV2	Selects data format for nav data; CIF (FURUNO) or NMEA
CIF BAUD RATE	Select baud rate of CIF data; 1200, 2400, 4800 bps

4. SYSTEM MENU

Item	Description
TVG CORRECTION	Changes TVG curve to compensate for absorption attenuation of ultrasonic wave in water. OFF, Standard TVG curve, 1/2, 1/2 of theoretical absorption value added to TVG curve, 1, Full theoretical absorption value added to TVG curve
UNIT	Select unit of depth measurement. m, meters; ft, feet; fm, fathom; HR, Hiro
V-MODE MANUAL TRAIN	Selects manual training sector width for the vertical fan mode. Half, half circle; Full, full circle
DEGAUSSING INTERVAL	Enter interval at which to have the screen degaussed. OFF de- gausses the screen at the maximum interval
FACTORY SETTING	Yes restores default system menu settings

APPENDIX 1 JIS CABLE GUIDE

Cables listed in the manual are usually shown as Japanese Industrial Standard (JIS). Use the following guide to locate an equivalent cable locally.

JIS cable names may have up to 6 alphabetical characters, followed by a dash and a numerical value (example: DPYC-2.5). For core types D and T, the numerical designation indicates the *cross-sectional Area (mm²)* of the core wire(s) in the cable. For core types M and TT, the numerical designation indicates the *number of core wires* in the cable.

 Core Type Double core power line Triple core power line 	2. Insulation Type P Ethylene Propylene Rubber	3. Sheath Type Y PVC (Vinyl)	DPYCY
M Multi core			
TT Twisted pair communicat	ions (1Q=quad cable)		
4. Armor Type	5. Sheath Type	Shielding Type	ТРҮСҮ
C Steel	Y Anticorrosive vinyl sheath	SLA All cores in one shield, plastic tape w/aluminum ta -SLA Individually shielded cores, plastic tape w/aluminum ta	
			MPYC-4
EX: DPYCYS	61_2 <u>LA</u> - <u>1.5</u> <u>MP</u> Designation type	$\frac{4}{4} - 4$	TTYCSLA-4

The following reference table lists gives the measurements of JIS cables commonly used with Furuno products:

Core		Cable	able		C	Core		
Туре	Area	Diameter	Diameter		Туре	Area	Diameter	Diameter
DPYC-1.5	1.5mm ²	1.56mm	11.7mm		TPYCY-1.5	1.5mm ²	1.56mm	14.5mm
DPYC-2.5	2.5mm ²	2.01mm	12.8mm		TPYCY-2.5	2.5mm ²	2.01mm	15.5mm
DPYC-4	4.0mm ²	2.55mm	13.9mm		TPYCY-4	4.0mm ²	2.55mm	16.9mm
DPYC-6	6.0mm ²	3.12mm	15.2mm		TPYCYSLA-1.5	1.5mm ²	1.56mm	13.9mm
DPYC-10	10.0mm ²	4.05mm	17.1mm		TTYC-7SLA	0.75mm ²	1.11mm	20.8mm
DPYC-16	16.0mm ²	5.10mm	19.4mm		TTYCSLA-1	0.75mm ²	1.11mm	9.4mm
DPYCY-1.5	1.5mm ²	1.56mm	13.7mm		TTYCSLA-1Q	0.75mm ²	1.11mm	10.8mm
DPYCY-2.5	2.5mm ²	2.01mm	14.8mm		TTYCSLA-4	0.75mm ²	1.11mm	15.7mm
DPYCY-4	4.0mm ²	2.55mm	15.9mm		TTYCY-4SLA	0.75mm ²	1.11mm	19.5mm
DPYCYSLA-1.5	1.5mm ²	1.56mm	11.9mm		TTYCYSLA-1	0.75mm ²	1.11mm	11.2mm
DPYCYSLA-2.5	2.5mm ²	2.01mm	13.0mm		TTYCYSLA-4	0.75mm ²	1.11mm	17.9mm
MPYC-2	1.0mm ²	1.29mm	10.0mm					
MPYC-4	1.0mm ²	1.29mm	11.2mm					
MPYC-7	1.0mm ²	1.29mm	13.2mm					
MPYCY-12	1.0mm ²	1.29mm	19.0mm					
MPYCY-19	1.0mm ²	1.29mm	22.0mm					

PACKING LIST 06AR-X-9852 -0 1/1		ユ-ド番号末尾の [**]は、選択品の代表J-ドを表します。 CODE NUMBER END NG W ITH **** ND CATES THE CODE NUMBER OF REPRESENTATIVE MATER ML .	型式/フード番号が 2段の場合、下段より上段に代わる過渡期品であり、どちらかが入っています。 なお、品質は変わりません。 T WO TYPES AND CODES MAY BE L&TED FOR AN ITEM . THE LOWER PRODUCT MAY BE SH PPED N PLACE OF THE UPPER PRODUCT.OIALLIY' B THE SAME . 예酪図の 寸法は、参考値 です。 D MENS DN S N DRAW NG FOR REFERENCE ONLY .)
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C1303-Z02-A

C1337-Z01-B

PACKING LIST Ref 0 1/1 DH-2422-113/115* A4 M N E 0.1 L N E DESCRIPTION/DOE 0.1/1 M N E M N E 0.1 1 A4 M N E M N E 0.1 1 DESCRIPTION/DOE 0.1/1 M N E M N E M N E 0.1 1 DESCRIPTION/DOE 0.1 M N E	ユ-ド蕾号末属の[**]は、選択品の代表コードを表します。 CODE NUMBER END NG WITH **** NDじATES THE CODE NUMBER OF REPRESENTAT WE MATER ML.	型式/コート番号が2段の場合、下段より上段に代わる過渡期品であり、どちらかが入っています。 なお、品質は変わりません。 TW 0 TYPES AND CODES MAY BE LBTED FOR AN ITEM. THE LOWER PRODUCT MAY BE SH PPED N PLACE OF THE UPPER PRODUCT.ONALITY E THE SAME.
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C1303-Z03-A

C1303-Z04-A

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A-6	06AR-X-9402 -2 1/1		数量 用途/编考 0.1V REMARKS	-			
	CODE NO. TYPE	SONAR	型名/擬格 DESORIPTIONS 06S4061-0 *50# 060E N0 000-126-156-19	81-545-0089-001+15M* 81-545-0089-001+15M* code No. 001-109-990-10	B1-545-0089-002 B1-545-0089-002 CODE NO CODE NO 001-110-000-10	81-545-0089-003+50M* CODE NO. 001-110-010-10	
	0	COLOR SECTOR SCANNING SONAR CH-37, CH-37BB S					
		工事材料表 INSTALLATION MATERIALS	番号 名 称 NO. NUME 7-7 16(組品) 1 CABLE ASSEMBLY	7-7.ル(組品) 2 CABLE ASSEMBLY	7-7.ル(組品) 3 CABLE ASSEMBLY	4 7-1 k (組品) 4 GABLE ASSEMBLY	
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-2 1/1 A-5	0, TY	-					
06AR-X-9855	DESCRIPTION/CODE No.	CH-3423 006-547-210-00	CH-3424-11/22 066-546-130-00 **	001-247-260-00			
PACKING LIST +-11-60/CH-3424-22-60	OUTLINE	343	200 180 180	240			
PACKING CH-3424-11-60/CH-3424-22-60	NAME L=v F UNIT	⊳.,° IN BODY FLANGE ASSEMBLY	地組立セット LL UNIT ASSEMBLY PARTS バーソナーオイル	PER SONAR DIL			

コージト

7525

MAIN BODY FLANGE ASSEMBLY

HULL UNIT ASSEMBLY PARTS

現地組立也小

SUPER SONAR OIL ጸ−/\° −'J+−オ⊀ル

그나 播号末尾の(**)(は、過択品の代表コートを表します。 CODE NUMBER ENDING WITH "**" INDICATES THE CODE NUMBER OF REPRESENTATIVE MATTERIAL.

TWO TYPES AND CODES MAY BE LISTED FOR AN ITEM. THE LOWER PRODUCT MAY BE SHIPPED IN PLACE OF THE UPPER PRODUCT. QUALITY IS THE SAME. 型式/コード番号が2段の場合、下段より上段に代わる過渡期品であり、どちらかが入っています。 なお、品質は変わりません。

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

THIO TYPES AND CODES MAY BE LISTED FOR AN ITEM. THE LOWER PRODUCT MAY BE SHIPPED IN PLACE OF THE UPPER PRODUCT. QUALITY IS THE SAME. (略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

FURUNO ELECTRIC CO ., LTD.

C1303-M02-C

型式/コード署号が2段の場合、下段より上段に代わる過渡期品であり、どちらかが入っています。 なお、品質は変わりません。

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FURUNO ELECTRIC CO ., LTD. (略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

C1303-M04-E

FURUNO ELECTRIC CO ., LTD.

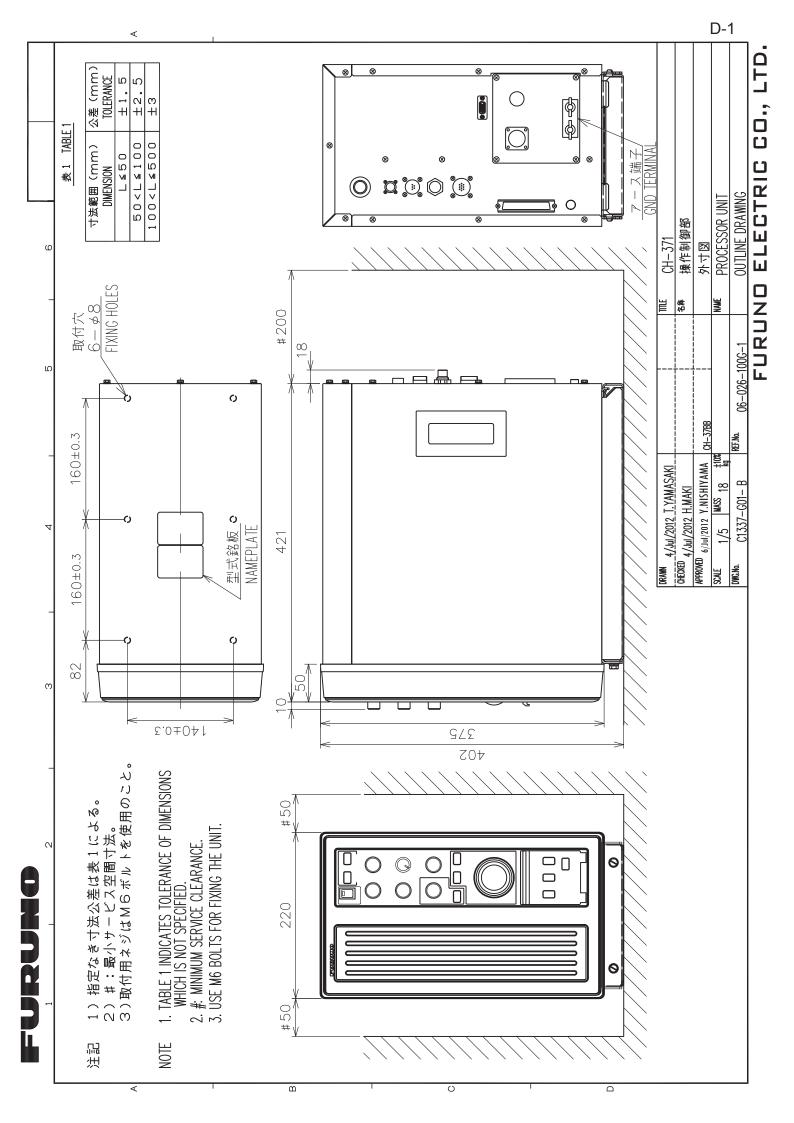
(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

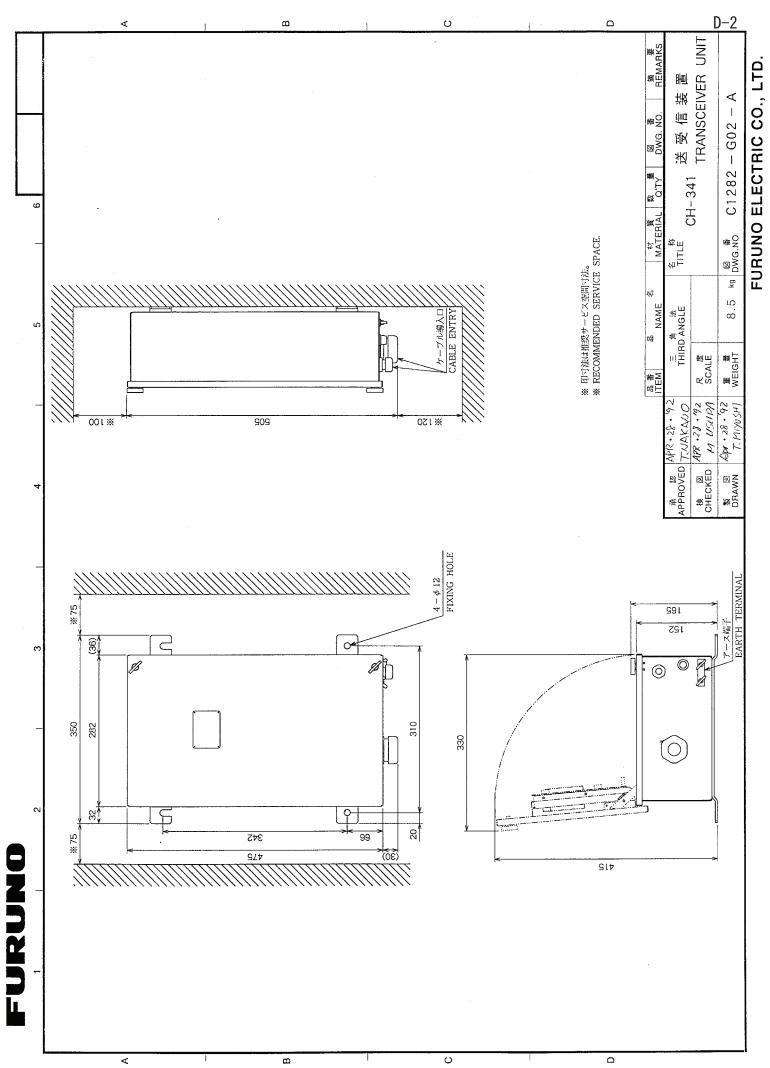
C1303-M03-C

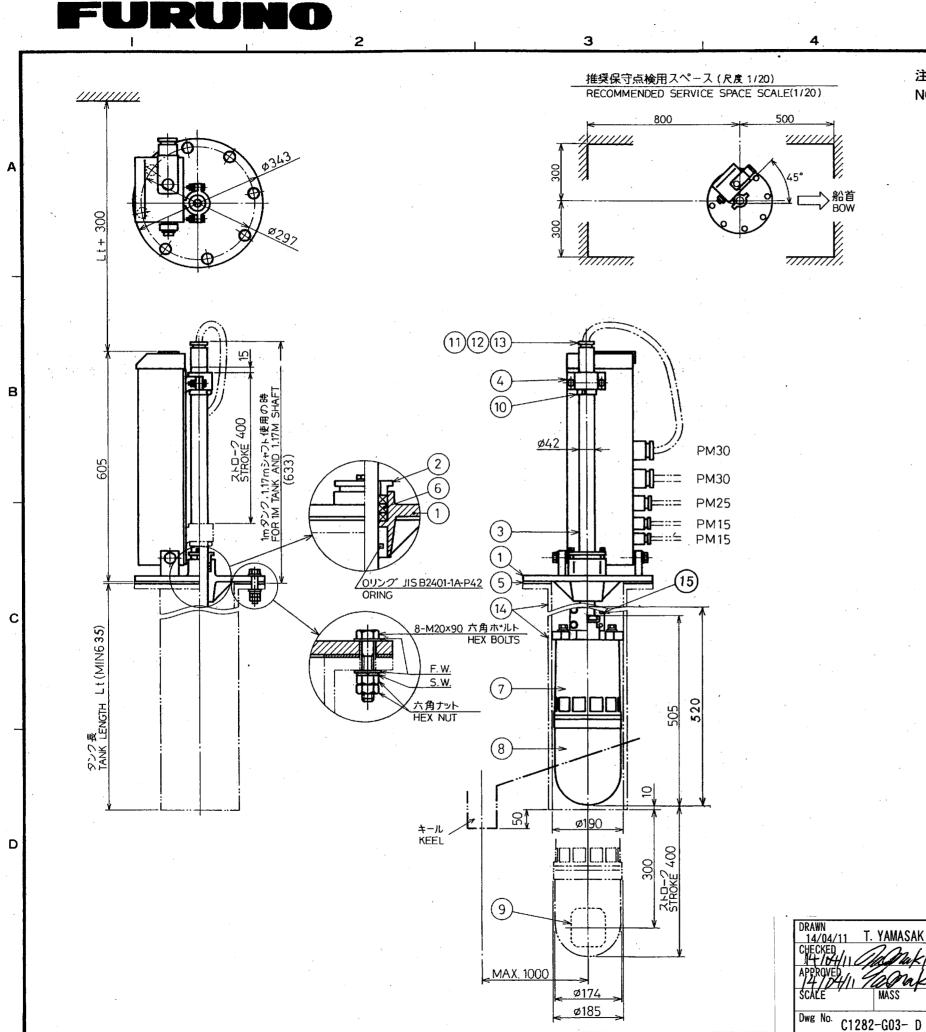
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注 NOTES:

1)装備位置は船首から1/3 (小型船で

5

- 2)上下シャフトの長さ(Ls)は、
 (Lt:格納タンクの長さ)
 Ls=Lt+110 (mm)
- 3) 上下装置の船首方向は左図の矢印(
- 4) ドーム内部保守点検のため、上下装置

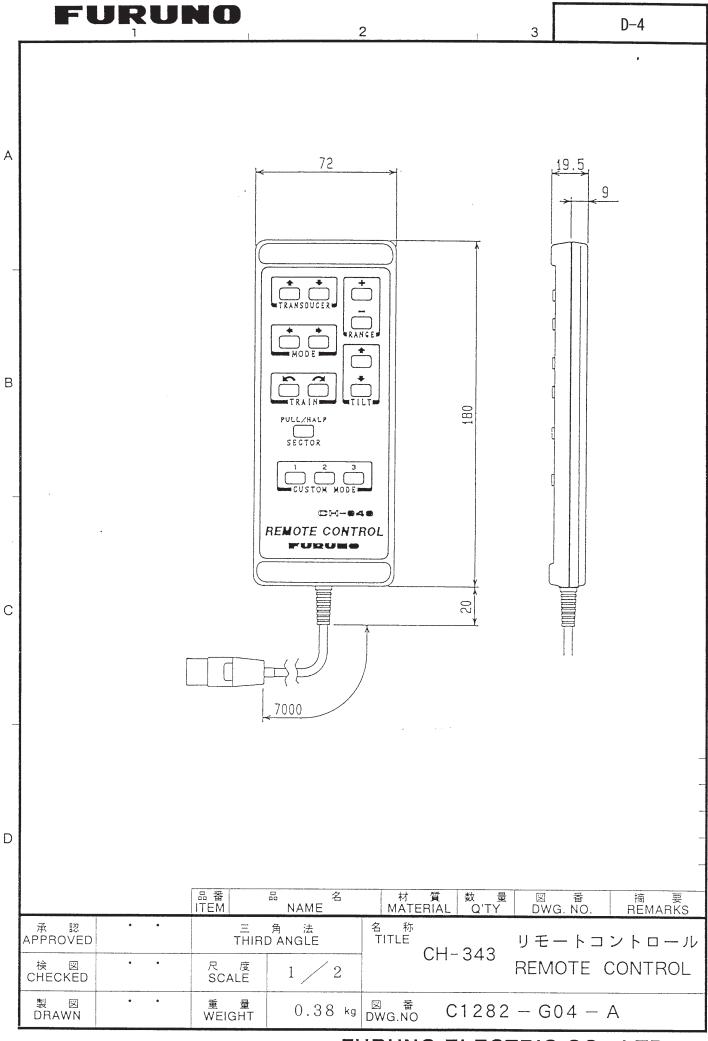
井等に 300mm × 300mm 程度の角次

- THE HULL UNIT IS GENERAL SMALL BOAT) OF THE SHIP'S - AFT LINE AND BESIDE THE KEEL LINE).
- 2) THE MAIN SHAFT SHOULD BE FOLLOWING EQUATION. Ls = Lt + 110 (mm)
- 3) \Rightarrow (ARROW) SHOWS FORE F
- 4) IF THE OVERHEAD CLEARA OBTAINED, MAKE A HOLE O FACILITATING INSTALLATION

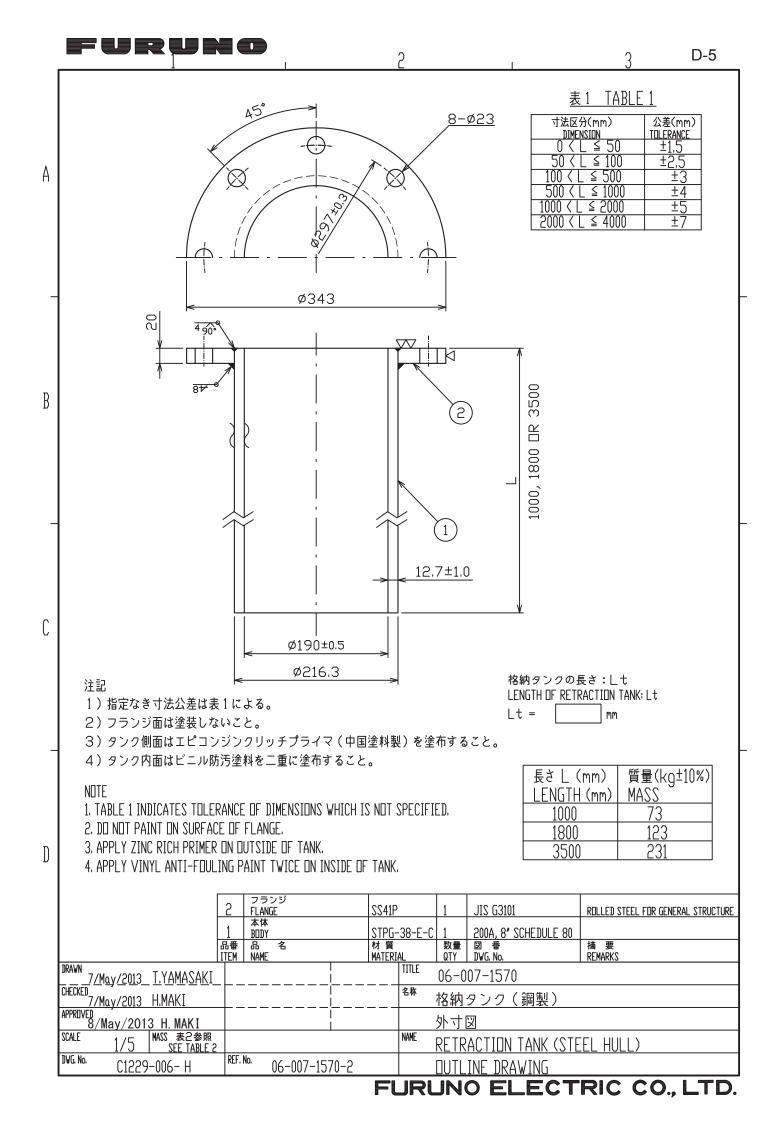
		:		
	15	シャフト保護金具 SHAFT RETAINER		
	14	格納タンク RETRACTION TANK		
-	13	ガスケット GASKET		
	12	座金 WASHER		
	- 11	締付グランド CABLE GLAND		
	10	ジュビリークリップ FASTENING BAND		
	9	送受波器 TRANSDUCER		-
	8	ドーム (D) SOUNDOME (D)		
	7.	ドーム (U) SOUNDOME (U)		
	6	グリスコットン GREASE COTTON		
	5	フランジバッキン GASKET		
· ·	4	パイプクランプ PIPE CLAMP		
	3	上下シャフト MAIN SHAFT		
	2	グリスコットン押え台 GREASE COTTON RETAIN	ER	-
	1	フランジ MAIN BODY FLANGE		
	品番 ITEM	品名 NAME		材 MA
(AMASAK I	:		T١	/PE
Maki			2	称
maki	CH-34	/37		
MASS	MODEL	BLOCK No.	N	AME .
G03- D	REF. No).		

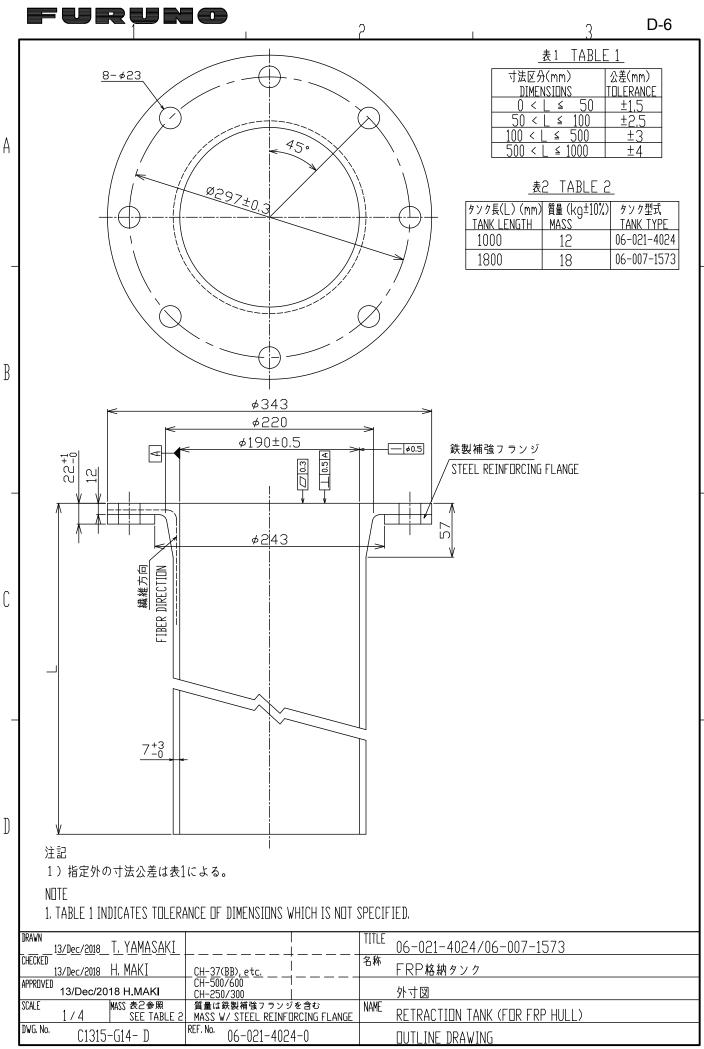
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)で示す。 上部には図示のスペースを設けるか、障害となる天を明ける。 Y PLACED ABOUT 1/3 (1/2 IN CASE OF LENGTH FROM THE BOW ON THE FORE KEEL LINE (LESS THAN 1000mm FROM CUT TO A LENGTH (Ls) GIVEN BY THE Lt: TANK LENGTH R HULL UNIT AND TANK. CE SHOWN IN THE DRAWING IS NOT 300mm × 300mm ON THE CEILING FOR AND FUTURE SOUNDOME SERVICE. 	· . (6		D-3	
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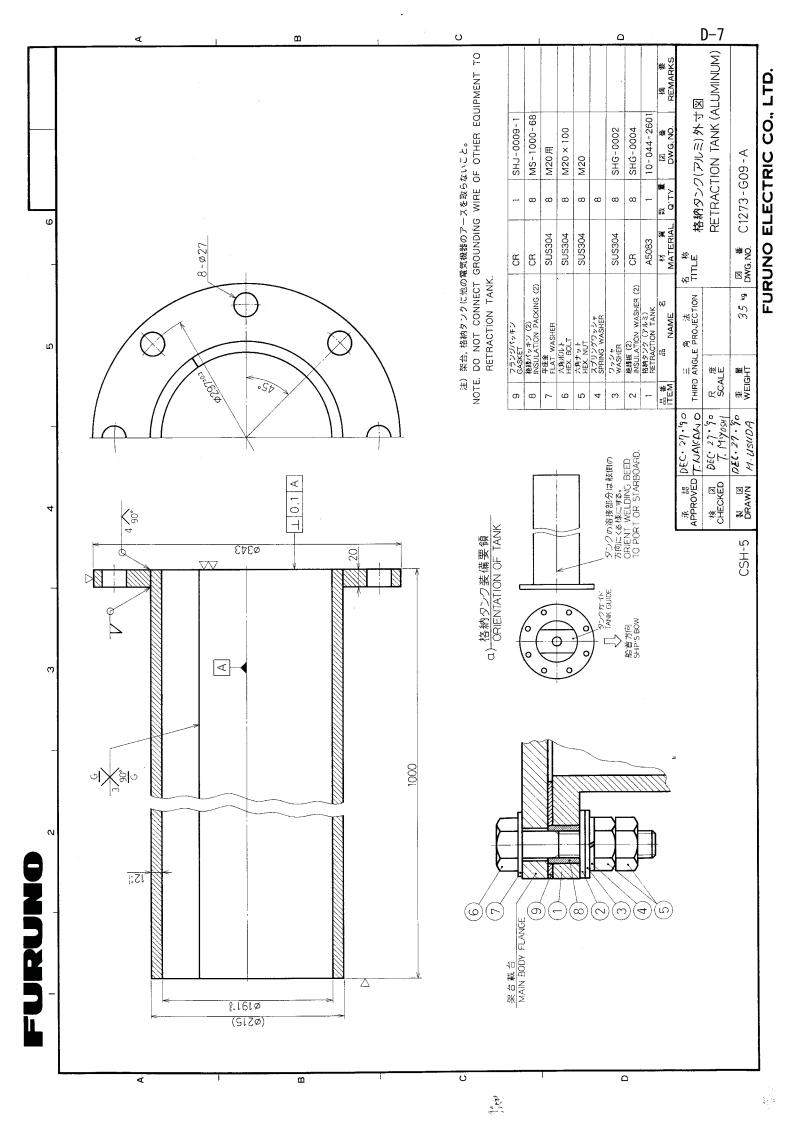


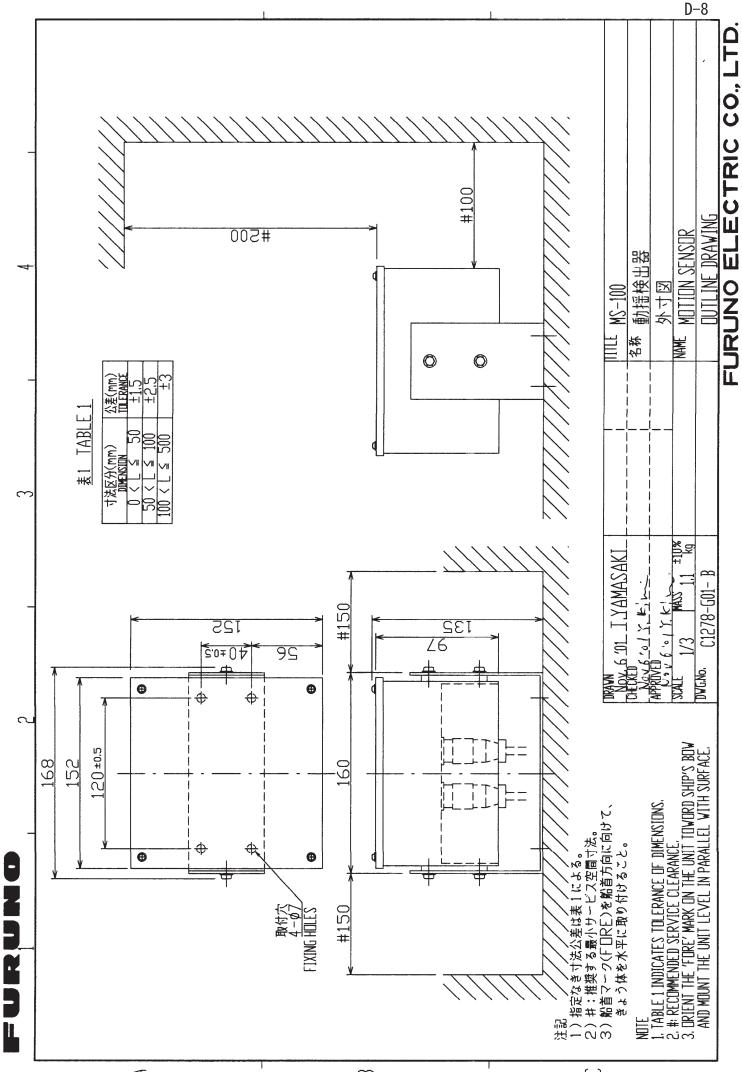
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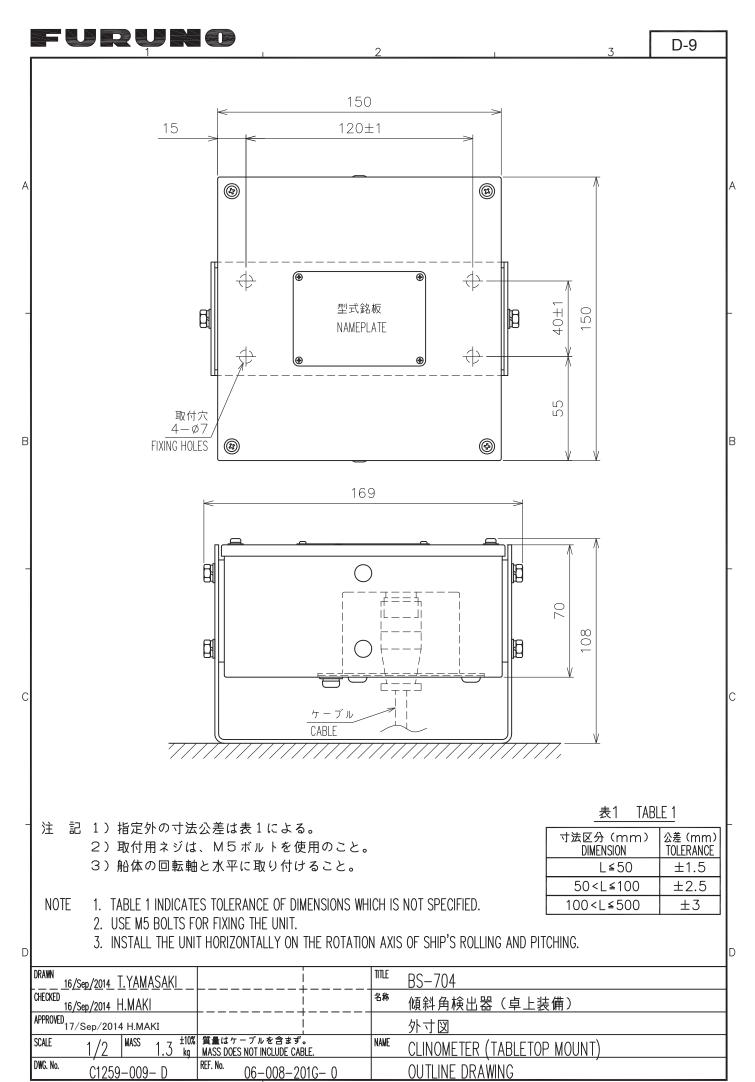
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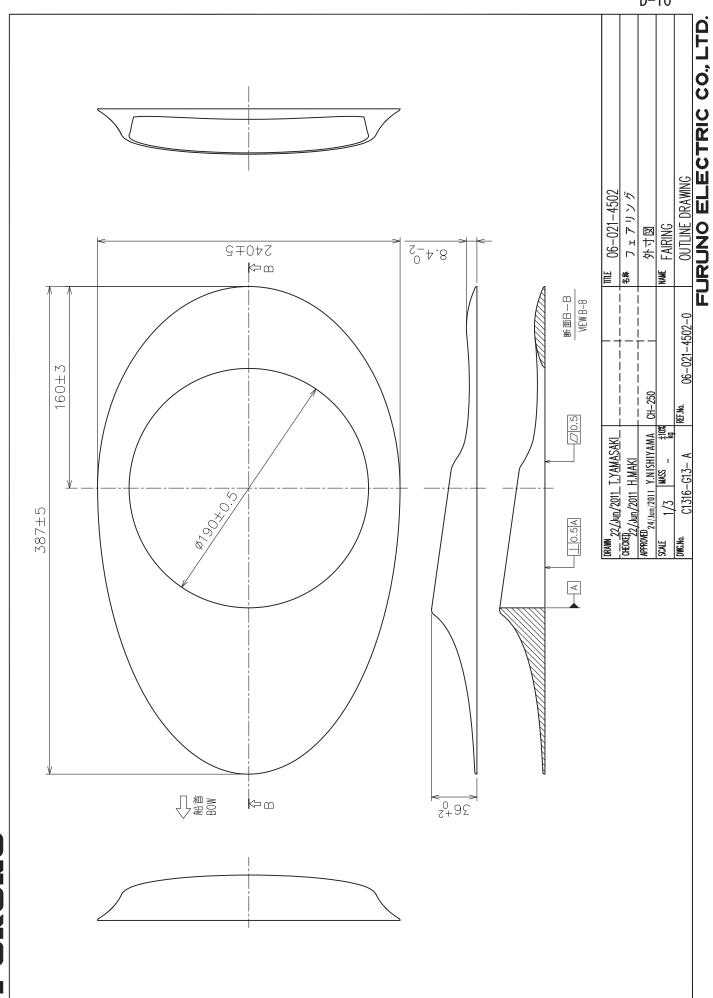


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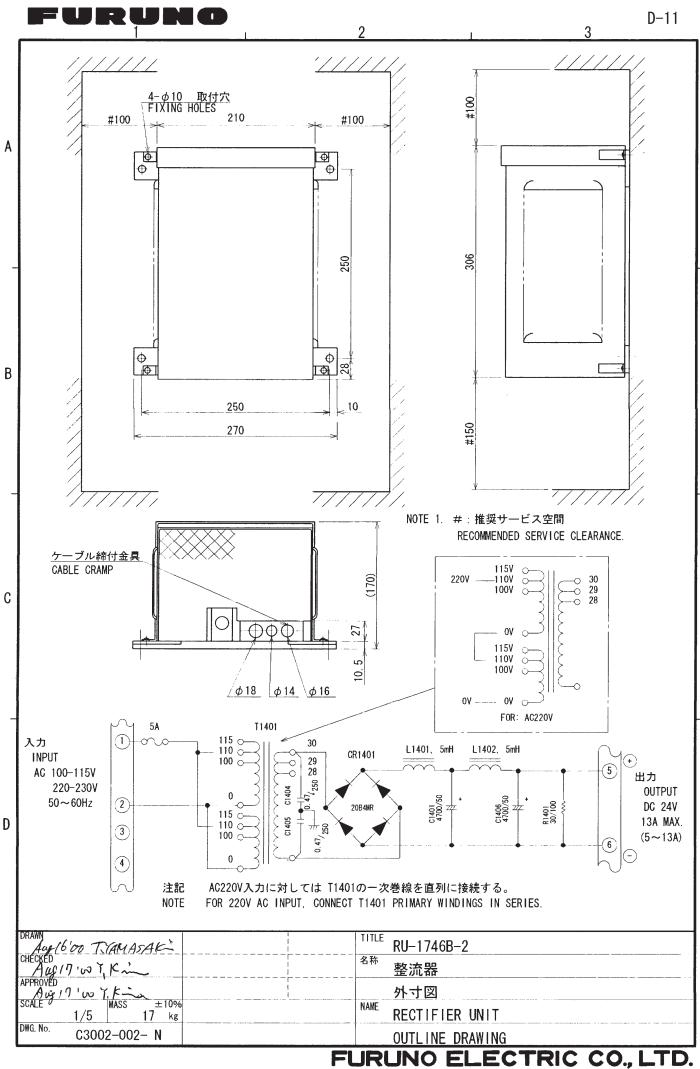
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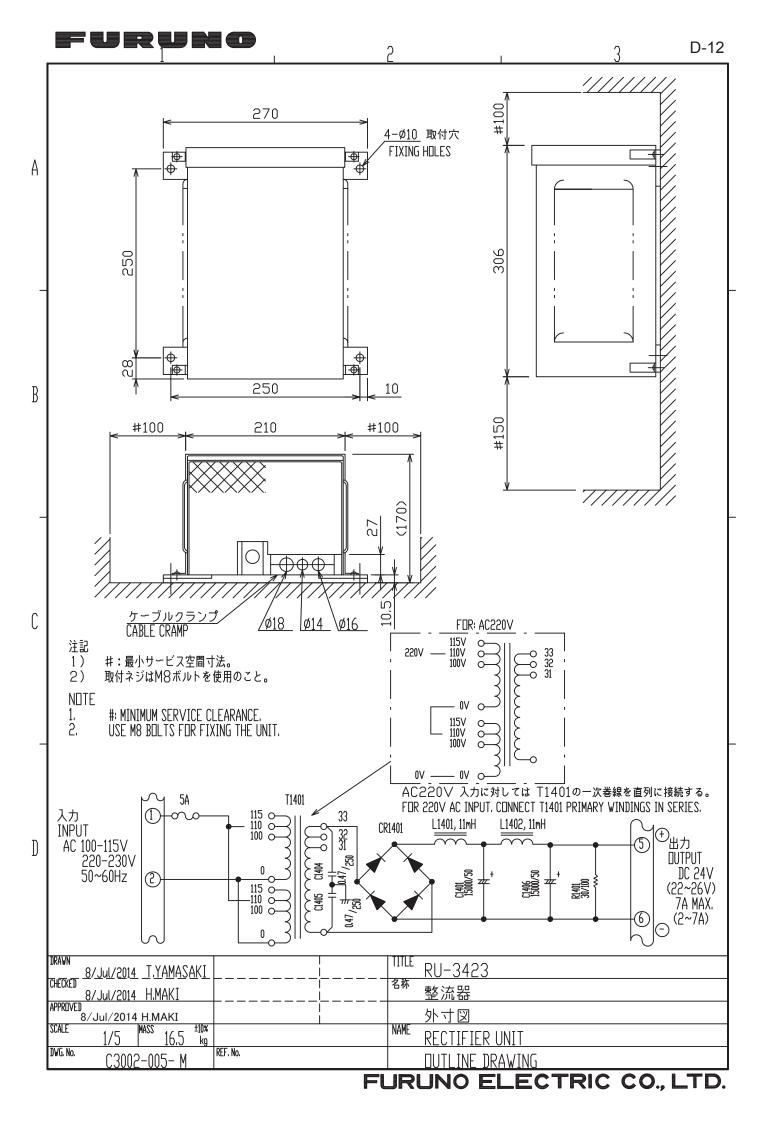


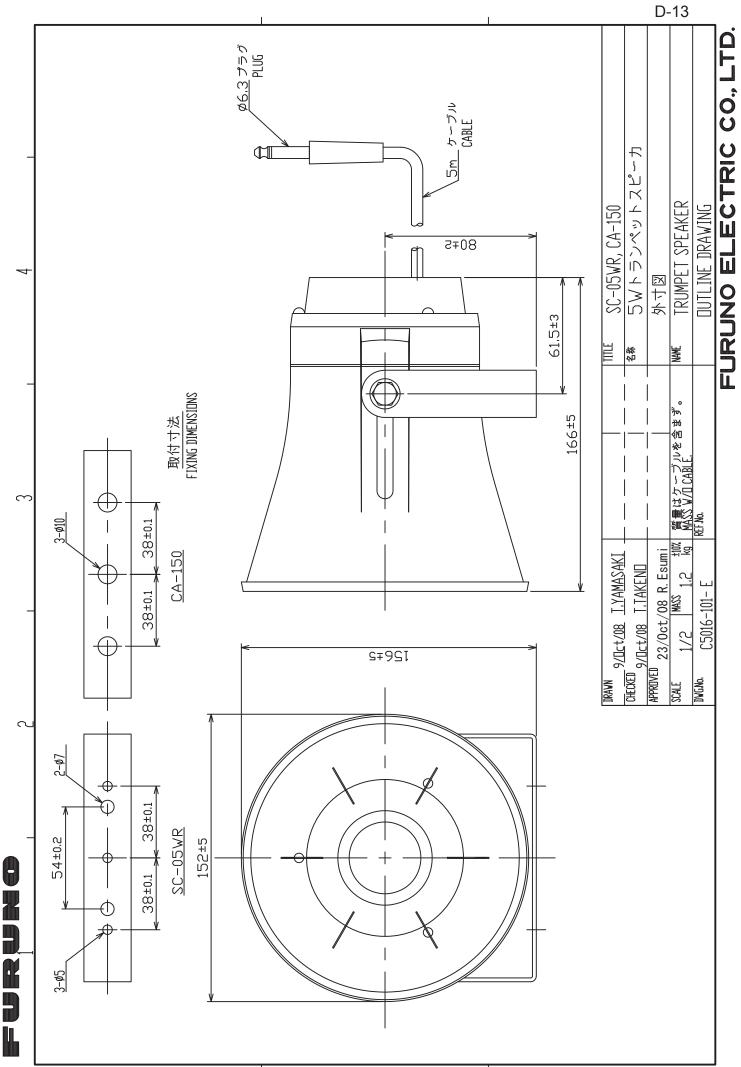
FURUNO ELECTRIC CO., LTD.

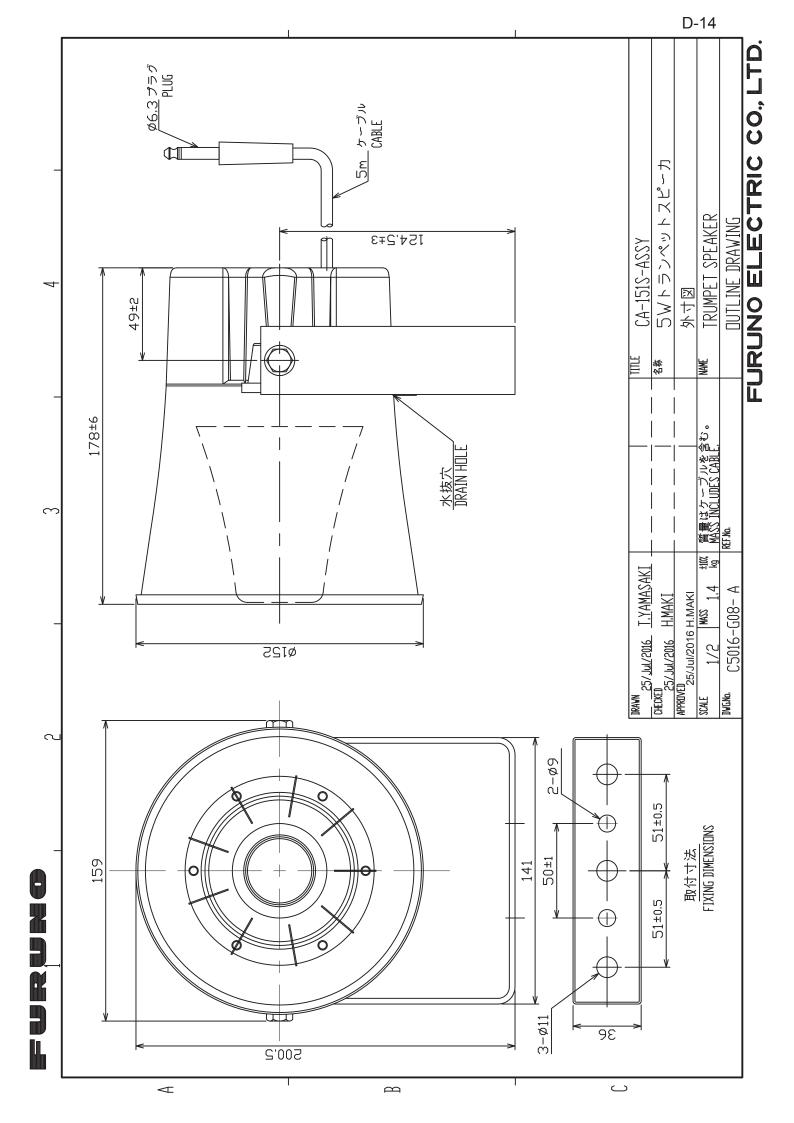


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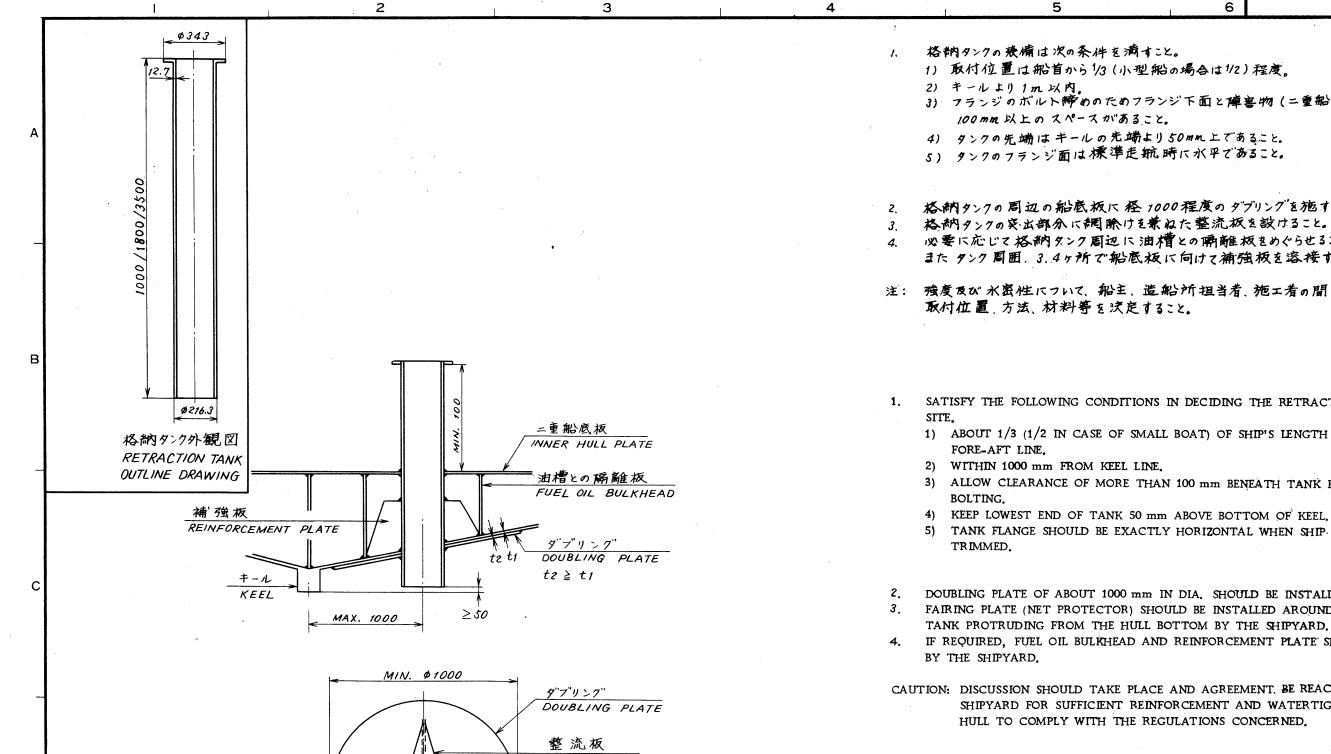










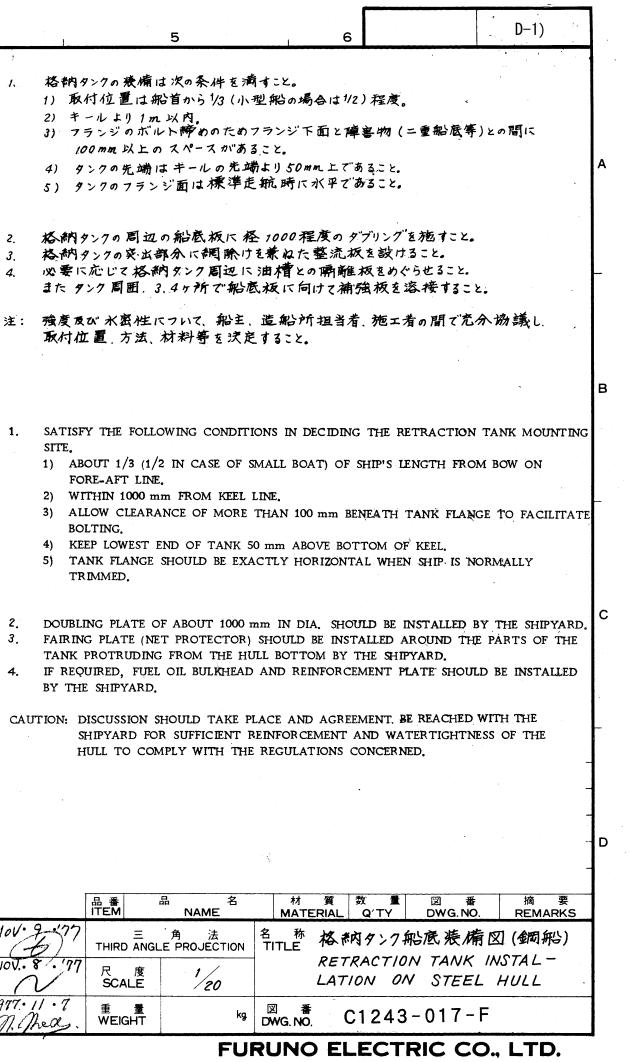


FAIRING PLATE

品番 ITEM 品 名 NAME 認 NoV· 9-17 名 称 TITLE 承 = ・角 法 APPROVED THIRD ANGLE PROJECTION NOV. 8 尺 度 SCALE X 検 1/20 CHECKED CSH-5 CSH-5 MARK-2 1977.11.7 製 図 DRAWN 重量 kg CH-12/14/16/24/26 WEIGHT

单位 UNIT: mm

D

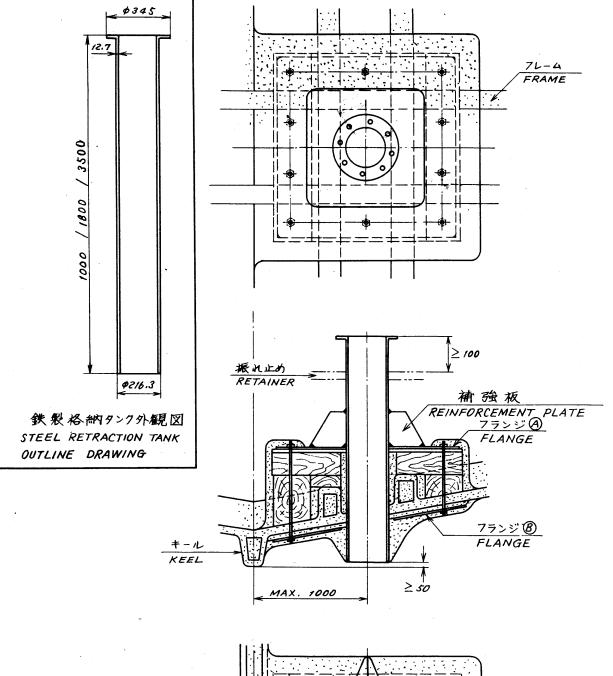


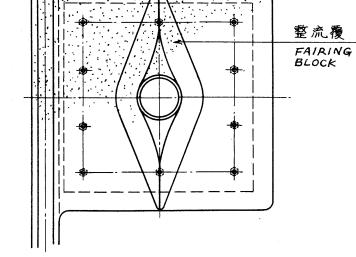


B

D

単位 UNIT:mm





- 格納タンクの装備は次の条件を満すこと。 1)取付位置は船首からり3(小型船の場合はり2)程度。
- 2) キールより1m以内。

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3) フランジのボルト神ののため、フランジ下面と障害物(二重船) 100 mm 以上のスペースがあること。

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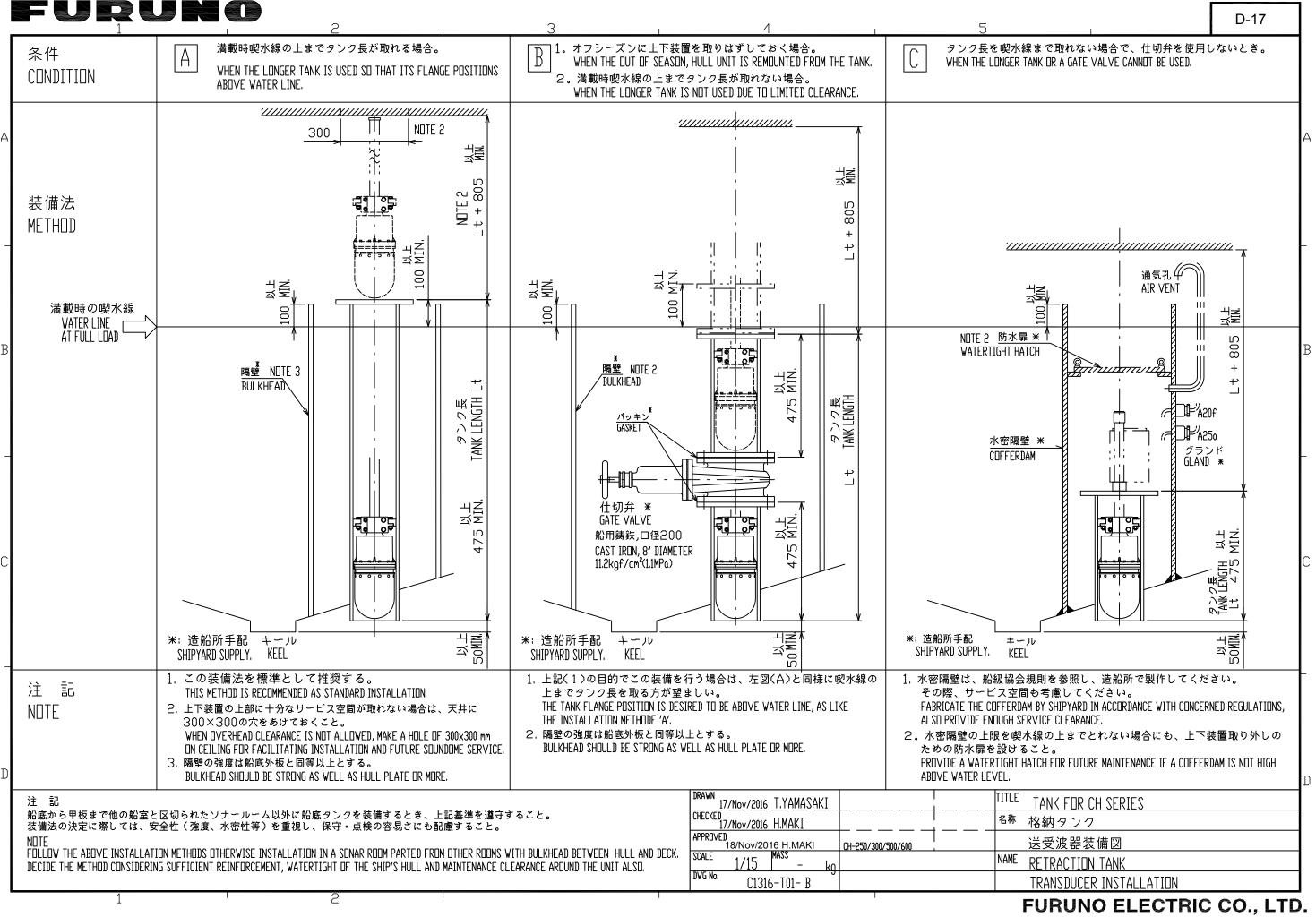
- 4) タンクの光端はキールの光端より50mm上であること。 5) タンクのフランジ面は標準走航時に水平であること。
- 裕納タンクの兼備は、次の要領を参考にして行うこと。 1) フレーム間の船底にタンクが通る穴をあける。 2.

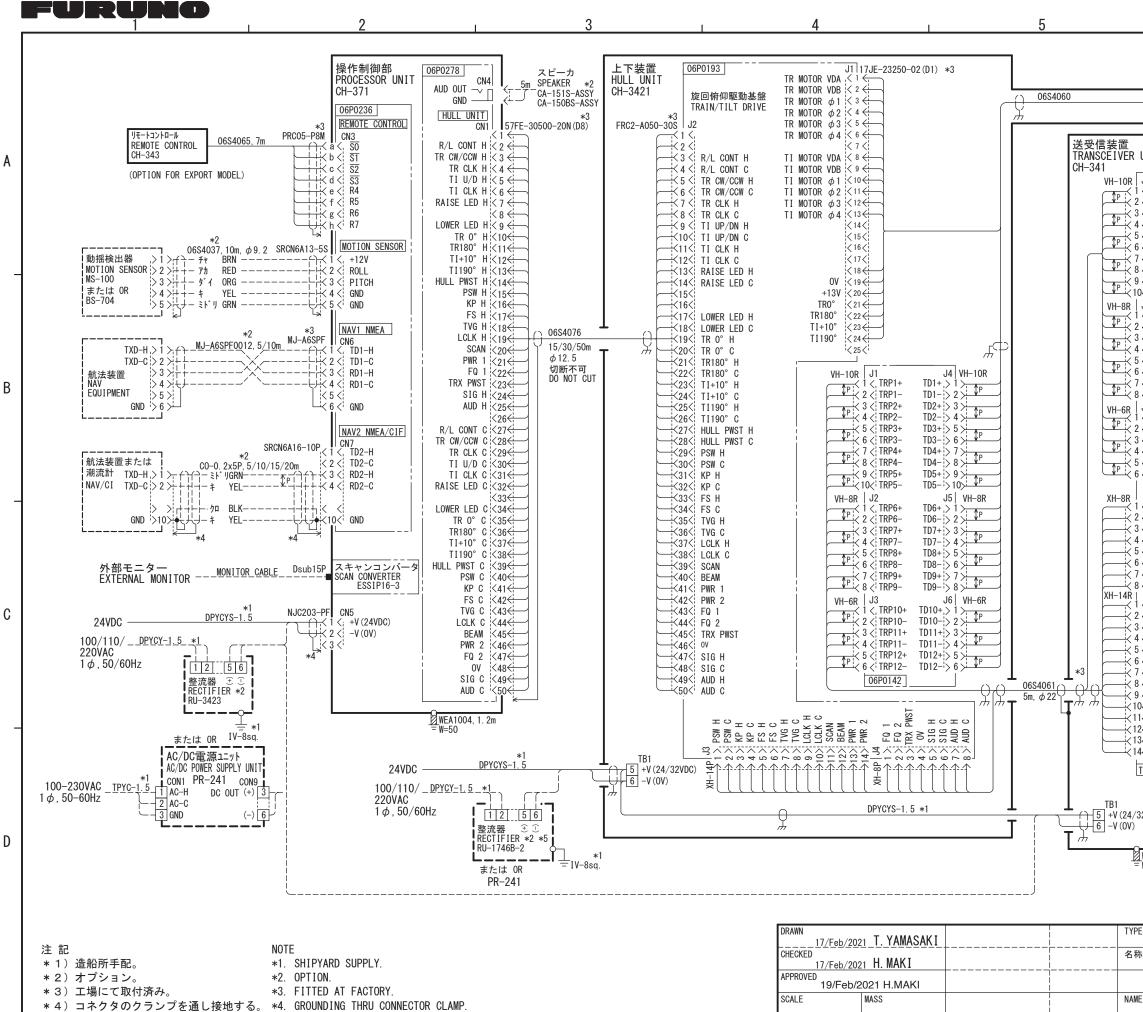
 - タングあるいはタンクと同径の中子を貫通させ、その回りに FRPでフレーム、船底間に固定する。 2)
 - フランジ(のの取付兄に合わせて取付台にボルトを立ててお ボルトを船底から貫通させる。 FRP 硬化後タンクあるいは中子を抜き取る。 3)
 - 4)
 - フランジ(タをタンクに客接する。 5)
 - フランジ(A)下面反びタンタ外周にFRP-鉄接着剤を塗 浸水を防ぐため充分にFRPで必要/固所を塗り固める。 6) 70 大による抵抗反び気泡発生を最少限にあさえる様
 - 必要に応じてタンクのフランジ面 下部 100mmの位置 8) またフランジ(A) 溶接時、タンクの周囲 3,4ヶ所でア
- 注: 強度及び水聚性について、船主、造船所担当者、施工者の 材料等を決定すること。
- 1. SATISFY THE FOLLOWING CONDITIONS IN DECIDING THE RETRACTION TAN 1) ABOUT 1/3 (1/2 IN CASE OF SMALL BOAT) OF SHIP'S LENGTH FROM BOW 2) WITHIN 1000 mm FROM KEEL LINE.
- 3) ALLOW CLEARANCE OF MORE THAN 100 mm BENEATH TANK FLANGE TO
- 4) KEEP LOWEST END OF TANK 50 mm ABOVE BOTTOM OF KEEL.
- 5) TANK FLANGE SHOULD BE EXACTLY HORIZONTAL WHEN SHIP IS NORMAL
- 2. INSTALL THE RETRACTION TANK REFERRING TO THE PROCEDURE BELOW. 1) CUT OUT A HOLE FOR PASSING THE TANK ON THE HULL PLATE.
- 2) PASS THE TANK OR A CORE HAVING THE SAME DIAMETER AS THE TAN BED WITH WOODEN BLOCK AND FRP AROUND THE TANK OR THE CORE.
- 3) WHEN FABRICATING THE MOUNTING BED, STAND THE BOLTS ON THE BI MAKE THE FLANGE (B) TO ENSURE FIXING OF THE FLANGE (A).
- 4) AFTER FRP IS STIFFENED, DRAW OUT THE TANK OR THE CORE FROM T
- 5) WELD THE FLANGE (A) TO THE TANK.
- 6) APPLY A STEEL-FR? ADHESIVE TO THE TANK AND THE FLANGE (A), AN PLACE. SETTLE THE FLANGE (A) WITH BOLTS AND NUTS.
- 7) APPLY FRP AROUND THE PARTS OF THE TANK PROTRUDING FROM THE MAKE A FAIRING BLOCK WITH FRP AROUND THE PROTRUDING PARTS O AERATION
- 8) IF REQUIRED, INSTALL A REINFORCEMENT PLATE WHEN THE FLANGE (A) PROVIDE REINFORCEMENT ANGLES BETWEEN THE TANK AND THE ADJAC
- CAUTION : DISCUSSION SHOULD TAKE PLACE AND AGREEMENT BE REACHED WIT REINFORCEMENT AND WATERTIGHTNESS OF THE HULL TO COMPLY V

			品 番 ITEM	品 名 NAME	
	承認 APPROVED	NOV. 9.177		角 法 ILE PROJECTION	名 TI
CSH-5	検 図 CHECKED	Nov. 8 . 177	尺 度 SCALE	1/20	
CSH-5 MARK-2 CH-12/14/16/24/26	製 図 DRAWN	1977. 11. 7 M. Dec.	重量 WEIGHT	kg	
		•			

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	1	6			D-1	*	
程度。		* 					
	贴底等)	との間に					
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の回り	にフラン	ジAの乗せ	とられる	取村台を作	E IJ		
立てて	あく。	をせかめれ	しば 7	ランジ ⑧ を	作り		
							\mathbf{F}
制を	塗布した	:後 ダンク3	を取り	っける。 民型に成型	97		
さえる	様努め	ること。	向けて	振れ止め	を苦ける	- y	
戸で	フランジ	一日に向	けて、 オ	前強板を道	を持する。		
施工和	首の間で	充分協言	義レ、	取付位置	、方法、		в
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BELOW E.	V.						
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E FROM	A THE M	OUNTING I	BED.				
A ,	AND INS	TALL THE	TANK	WITH FLAN	ige (A)	IN	
OM TI	HE HULL	BOTTOM	FORS	JFFICIENT F	EINFORC	EMENT.	F
				MIZE THE E			1
		VELDED TO ULKHEAD (TANK, IT LING,	IS ADVIS	SABLE TO]
CHED V	VITH THE	SHIPYAR	FOR S	UFFICIENT		•	
		•		S CONCERNI	ED,		
名	材	· 質 数	±	图 番	捕	新 要	-
<u> </u>	MATI	ERIAL Q	<u>'TΥ</u>	DWG.NO.	RE	MARKS	-
TION	名称 TITLE			19船底装 RACTION		RP船)	
0			1	N ON F			
kg		C12	243	-019-1			1
	Dirid. IN						1

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*5) 出力タップを30Vに変更する。 *5. CHANGE OUTPUT TAP TO 30V.

CO-0. 2x5P: CO-SPEVV-SB-C 0. 2x5P, φ13. 5

06-026-0001-0

REF. No.

DWG. No.

C1337-C01- H

		0-1
	6	
	送受波器ドーム	
	SOUNDOME CH-3422	
	011-3422	
	*3 MR-60F J1	
	$1 > 1 > 1$ MOTOR $\phi 4$	
UNIT	$2 > TI MOTOR \phi 3$ $2 > TI MOTOR \phi 2$	
110	$4 > TI MOTOR \phi 1$ 4 > TI MOTOR VDA	
J10 1 <, TRP1+	6 > TI MOTOR VDB	
2 < TRP1- 3 < TRP2+	$\Rightarrow 7 > 0V$ $\Rightarrow 8 > TR MOTOR \phi 4$	
4 < TRP2-	$\langle \downarrow \rangle > 9 > TR MOTOR \phi 3$	
5 < TRP3+ 6 < TRP3-	() $()$	
7 < TRP4+	12> TR MOTOR VDA	
8 < TRP4– 9 < TRP5+	13 TR MOTOR VDB 14 14 $0V$	F
10< [¦] TRP5-	>15>	
J11 1 <, TRP6+	>16> +13V >17> +13V	
2 < TRP6- 3 < TRP7+	>18>+13V >19>+13V	
4 <¦ TRP7-	>20>	
5 < TRP8+ 6 < TRP8-	21> 0V >22> 0V	
7 < TRP9+	>23> 0V	
8 < TRP9-	>24> 0V >25>	
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6 < TRP12-	>30> 	
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4 < ov 5 < SIG H	→48> TD3+	
6 < SIG C	→ 34> TD4- → 49> TD4+	
7 < AUD H 8 < AUD C		
J9 ∠;PSW H	\rightarrow 50>; TD5+ \rightarrow 36>; TRP6-	
2 < PSW C	>51> TRP6+ >37> TRP7-	
3 < KP H 4 < KP C	>52> TRP7+	
5 < FS H	→ 38> TRP8- → 53> TRP8+	
6 < FS C 7 < TVG H	\rightarrow 39> TRP9-	
8 < TVG C	→54> TRP9+ →40> TRP10-	
9 < LCLK H 10< LCLK C	→55> TRP10+	
1< SCAN	\rightarrow 41> TRP11- \rightarrow 56> TRP11+	
12< BEAM 13< PWR 1	→42> TRP12-	F
14< PWR 2	>57> TRP12+	
TXA 06P0190	>45>	
	>58> >59>	
(32VDC)	└───- ⁱ →60> ⁱ GND	
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PE		
CH-37BB		
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相互結線	図	<u> </u>
カラーセ 相互結線 ^{ME} COLOR SE		<u> </u>